

# Measuring Interactions from Time Series

Information-theory-based  
techniques

**measuring interactions****information-theory**

**basic idea:** interaction  $\Leftrightarrow$  information flow

- the “stronger” the information flow, the stronger the interaction
- information flow from one system to another indexes directionality

characterize information with Shannon entropy  $H = - \sum_i p_i \log p_i$

$p$  is the (normalized) probability for an event / state / amplitude / ... to occur

estimate probability with  $p_i = \lim_{N \rightarrow \infty} N_i / N$

where  $N$  is the total number of events / states / amplitudes / ...

**measuring interactions*****strength of interaction:***

given systems X and Y, the mutual information is defined as:

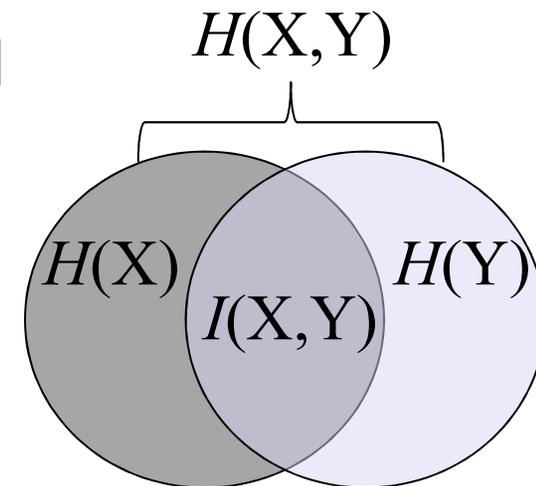
$$I(X, Y) = H(X) + H(Y) - H(X, Y)$$

information generated by system X is characterized by the Shannon entropy:

$$H(X) = - \sum_i^N p_X(i) \log p_X(i)$$

joint information is characterized by the Shannon entropy:

$$H(X, Y) = - \sum_{i,j}^N p_{X,Y}(i, j) \log p_{X,Y}(i, j)$$

**information-theory****mutual information**

**measuring interactions*****strength of interaction:*****information-theory****relative entropy**

relative entropy (also known as Kullback-Leibler divergence):

$$H_{\text{rel}}(X|Y) = - \sum_i^N p_X(i) \log \frac{p_X(i)}{p_Y(i)}$$

- characterizes the similarity between the probability distributions.
- relative entropy is asymmetric:  $H_{\text{rel}}(X|Y) \neq H_{\text{rel}}(Y|X)$
- in general  $H_{\text{rel}}$  is positive, and zero for identical systems

→ alternative definition of mutual information:

$$I_{\text{rel}}(X|Y) = - \sum_{i,j}^N p_{X,Y}(i,j) \log \frac{p_{X,Y}(i,j)}{p_X(i)p_Y(j)}$$

characterizes *relative* difference between respective probability density distributions and the joint distribution density

## **measuring interactions**

### ***strength of interaction:***

## **information-theory**

### **mutual information**

#### properties of mutual information:

- symmetric:  $I(X, Y) = I(Y, X)$
- $I(X, Y) = 0$  for independent (non-interacting) systems
- $I(X, Y) = \max$  for identical (fully synchronized) systems
- $I(X, Y)$  increases monotonically with increasing coupling strength → data-driven estimator for strength of interaction

#### disadvantages:

- only considers (single/joint) probability density distributions
- no information about dynamics
- can not explicitly distinguish between information exchange and joint information (e.g. due to common input or joint past)

**measuring interactions*****strength of interaction:***

extensions:

time-delayed mutual information

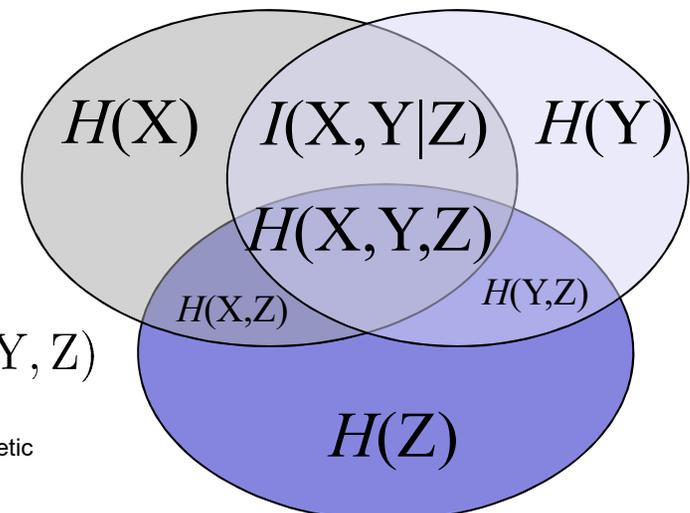
(Kaneko, Physica D 23, 436, 1986)

partial (or conditional) mutual information

(S. Frenzel &amp; B. Pompe, PRL 99, 204101, 2007)

- part of mutual information of two random quantities that is not contained in a third one
- similar to partial correlation
- can also detect directionality\*

$$I(X, Y|Z) = H(X, Z) + H(Y, Z) - H(Z) - H(X, Y, Z)$$



\* K. Hlaváčková-Schindler, M. Paluš, M. Vejmelka & J. Bhattacharya. Causality detection based on information-theoretic approaches in time series analysis. Physics Reports, 441, 1-46, 2007

**measuring interactions*****direction of interaction:*****information-theory****transfer entropy**

aim: characterize flow of information between systems  $X$  and  $Y$

idea: replace (static) probability density distributions by transition probability densities (cf. Entropies)

given: time series  $\mathbf{v}$ :  $v_1, v_2, \dots, v_N$  of some observable  $\mathbf{x}$  and  
time series  $\mathbf{w}$ :  $w_1, w_2, \dots, w_N$  of some observable  $\mathbf{y}$

1) incorporate time-dependence by relating previous samples  $v_i$  and  $w_i$  to predict the next value  $v_{i+1}$  (cf. N. Wiener),

2) consider generalized Markov condition ( $p$  = transition probability density):

$$p(v_{i+1} | \mathbf{v}_i, \mathbf{w}_i) = p(v_{i+1} | \mathbf{v}_i)$$

**measuring interactions**

***direction of interaction:***

**information-theory**

**transfer entropy**

3) if systems X and Y independent → Markov condition fulfilled

4) use relative entropy concept to quantify *incorrectness* of Markov condition; with this, transfer entropy is defined as:

$$T_{Y \rightarrow X} = \sum_i^N p \left( v_{i+1}, \mathbf{v}_i^{(k)}, \mathbf{w}_i^{(l)} \right) \log \frac{p \left( v_{i+1} | \mathbf{v}_i^{(k)}, \mathbf{w}_i^{(l)} \right)}{p \left( v_{i+1} | \mathbf{v}_i^{(k)} \right)}$$

$(l, k)$  denote orders of Markov processes

$T_{X \rightarrow Y}$  defined in complete analogy

**measuring interactions*****direction of interaction:*****information-theory****transfer entropy**

## properties of transfer entropy

- can detect direction of information flow since  $T_{Y \rightarrow X} \neq T_{X \rightarrow Y}$
- unbounded, needs suitable definition of directionality, e.g.

$$T := T_{Y \rightarrow X} - T_{X \rightarrow Y} \begin{cases} > 0 : Y \text{ drives } X \\ = 0 : \text{no or symmetric bidir. coupling} \\ < 0 : X \text{ drives } Y \end{cases}$$

- depends on coupling strength  $\rightarrow$  data-driven estimator for direction of interaction
- for Gaussian distributed data, transfer entropy equals Granger causality
- similar to conditional mutual information (replace system  $Z$  by e.g., past of system  $Y$ )

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***direction of interaction:***

**information-theory**

**transfer entropy**

extensions:

- multivariate (partial) transfer entropy
- various estimation techniques
- estimators for transient signals\* and delay-systems\*\*

\* H. Dickten, K. Lehnertz K. Identifying delayed directional couplings with symbolic transfer entropy. Phys Rev E 90, 062706, 2014

\*\* M. Martini, TA Kranz, T Wagner, K Lehnertz K. Inferring directional interactions from transient signals with symbolic transfer entropy. Phys Rev E 83, 011919, 2011

## **measuring interactions**

## **information-theory**

### ***strength and direction of interaction***

how to estimate probability density distributions and the joint distribution densities from time series?

- counting (cumbersome)
- various binning techniques
- nearest neighbor estimators (e.g. Kozachenko-Leonenko)
- correlation sum (via phase-space embeddings)
- symbolization (e.g. based on permutation entropy\*)

**measuring interactions**

***strength and direction of interaction***

estimators based on the concept of symbolic dynamics and on symbolization

***symbolic dynamics:*** modeling a smooth dynamical system by a *discrete space* consisting of infinite *sequences of symbols*, each of which corresponds to a state of the system, with the dynamics (evolution) given by the shift operator

***symbolization:*** generate symbols via delay embedding

$$\mathbf{s}_i := \left( v_{i+(j_1-1)\tau}, v_{i+(j_2-1)\tau}, \dots, v_{i+(j_m-1)\tau} \right)$$

where

$$v_{i+(j_1-1)\tau} \leq v_{i+(j_2-1)\tau} \leq \dots \leq v_{i+(j_m-1)\tau}$$

→ symbol  $\hat{\mathbf{s}}_i := (j_1, j_2, \dots, j_m)$

**information-theory**

***an example***

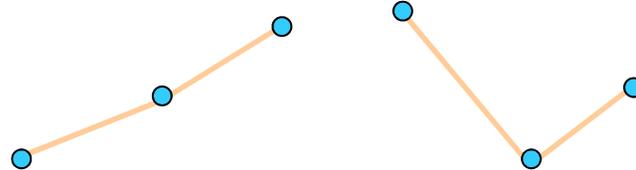
**measuring interactions**

***strength and direction of interaction***

**information-theory**

***an example***

embedded data: ( 3, 5, 9) (10, 1, 6)



symbols  $\Rightarrow$

(1, 2, 3)

(1, 3, 2)

***permutation entropy:***  $H(m) = - \sum_{i=1}^{m!} \hat{s}_i \log \hat{s}_i$

normalization:  $0 \leq H = \frac{H(m)}{\log(m!)} \leq 1$

$H \rightarrow 0$  for deterministic systems,  $H \rightarrow 1$  for stochastic systems

**measuring interactions****information-theory*****strength and direction of interaction******an example***

given time series of systems X and Y:

- estimate permutation entropy from windowed data
- investigate changing tendency of permutation entropies

$$S(w_i) = \begin{cases} +1 & : \text{if } H(w_i) < H(w_{i+1}) \\ -1 & : \text{else} \end{cases}$$

- characterize in-step behavior of pairs of permutation entropies

$$\gamma := \sum_{i=1}^{N_w} S_X(w_i) S_Y(w_i)$$

- $\gamma = 0$  for independent systems;  $\gamma \rightarrow 1$  for synchronized systems;  $\gamma$  increase monotonically with increasing coupling strength  $\rightarrow$  data-driven estimator for strength of interaction

**measuring interactions****strength and direction of interaction****information-theory****an example**

given time series of systems X and Y:

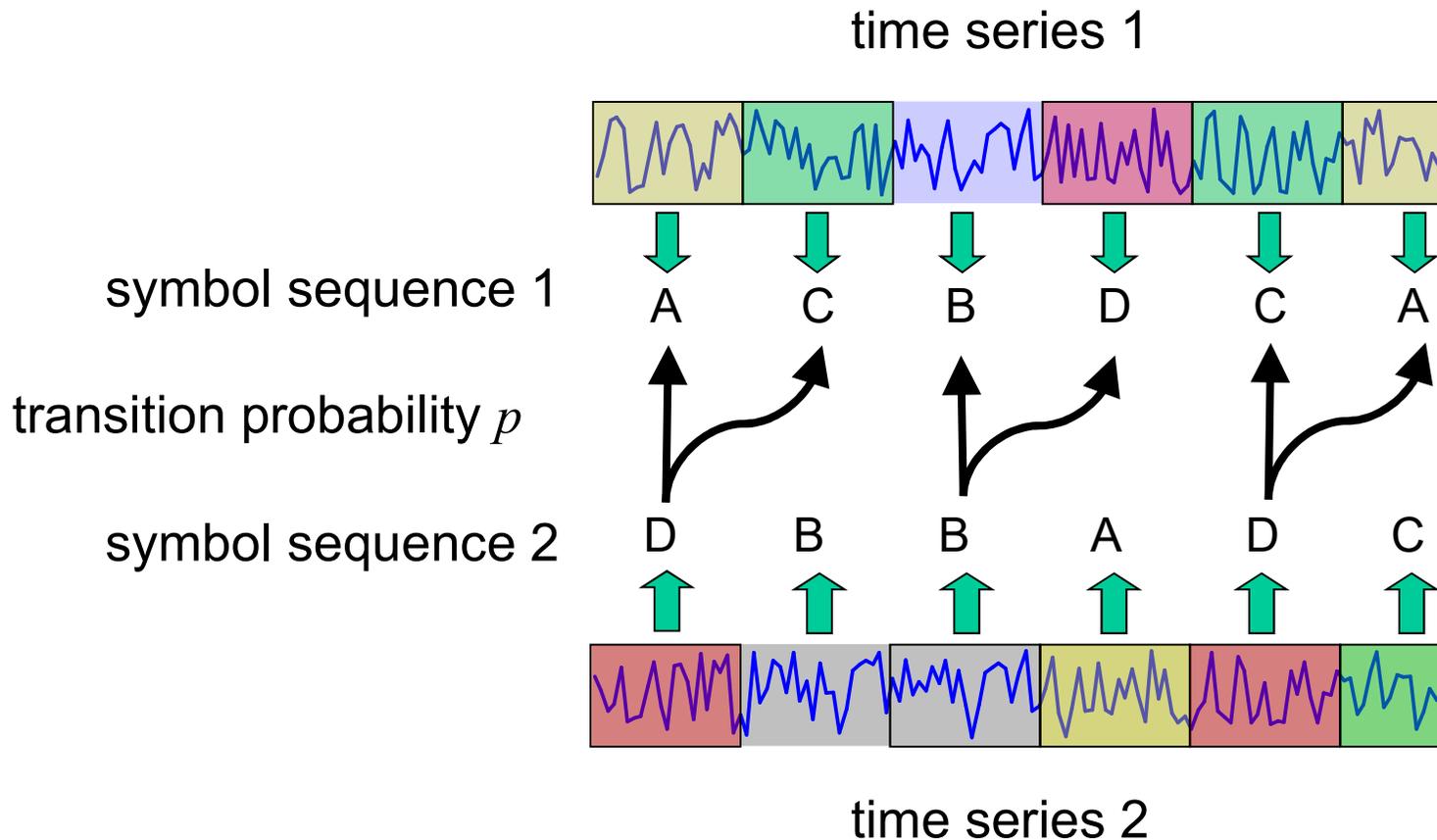
- for estimating probability density distributions and the joint distribution densities:  
replace probabilities of data with probabilities of symbols  
count symbols ( $\rightarrow$  very fast)
- symbolic transfer entropy:

$$T_{Y \rightarrow X}^S = \sum_{\hat{v}_{i+1}, \hat{\mathbf{v}}_i^{(k)}, \hat{\mathbf{w}}_i^{(l)}} p \left( \hat{v}_{i+1}, \hat{\mathbf{v}}_i^{(k)}, \hat{\mathbf{w}}_i^{(l)} \right) \log \frac{p \left( \hat{v}_{i+1} | \hat{\mathbf{v}}_i^{(k)}, \hat{\mathbf{w}}_i^{(l)} \right)}{p \left( \hat{v}_{i+1} | \hat{\mathbf{v}}_i^{(k)} \right)}$$

- see properties of transfer entropy
- easy-to-use data driven estimator for direction of interaction

**measuring interactions**  
**strength and direction of interaction**

**information-theory**  
**an example**



measuring interactions

*strength and direction of interaction*

information-theory

*an example*

diffusively coupled Rössler oscillators  
(100 realizations)

$$\dot{x}_{1,2} = -\Omega_{1,2}y_{1,2} - z_{1,2} + c_{1,2}(x_{2,1} - x_{1,2})$$

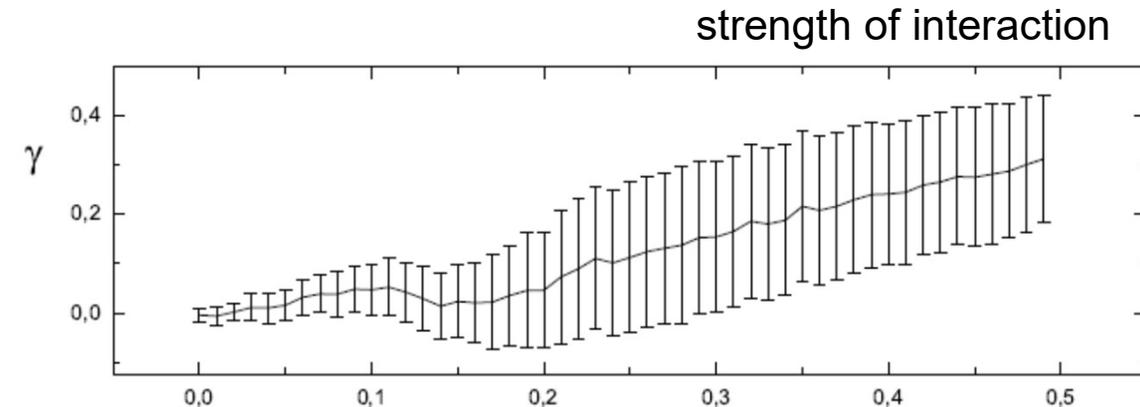
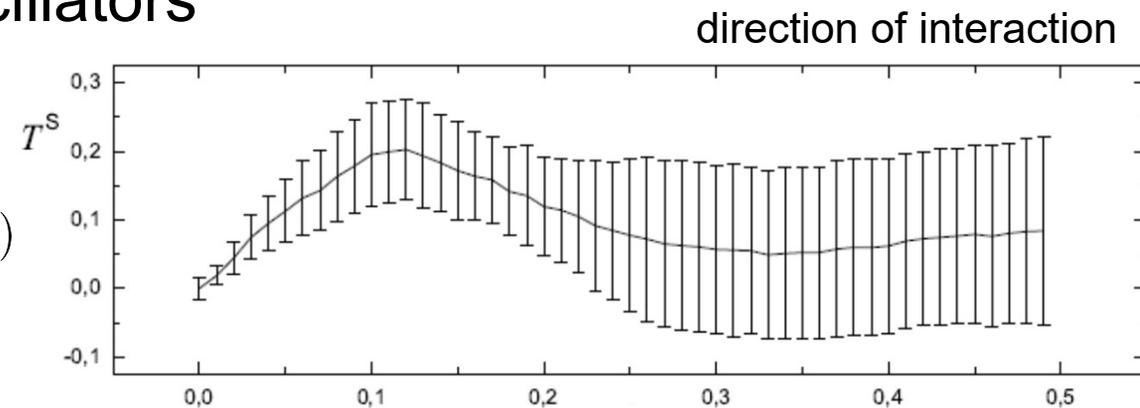
$$\dot{y}_{1,2} = \Omega_{1,2}x_{1,2} + 0.165y_{1,2}$$

$$\dot{z}_{1,2} = 0.2 + z_{1,2}(x_{1,2} - 10)$$

$$\Omega_{1,2} \in \mathcal{N}(0.89; 0.1)$$

$$c_1 = 0$$

$$c_2 = c$$



coupling strength  $c$

## measuring interactions

**strength and direction of interaction**

## information-theory

**an example**

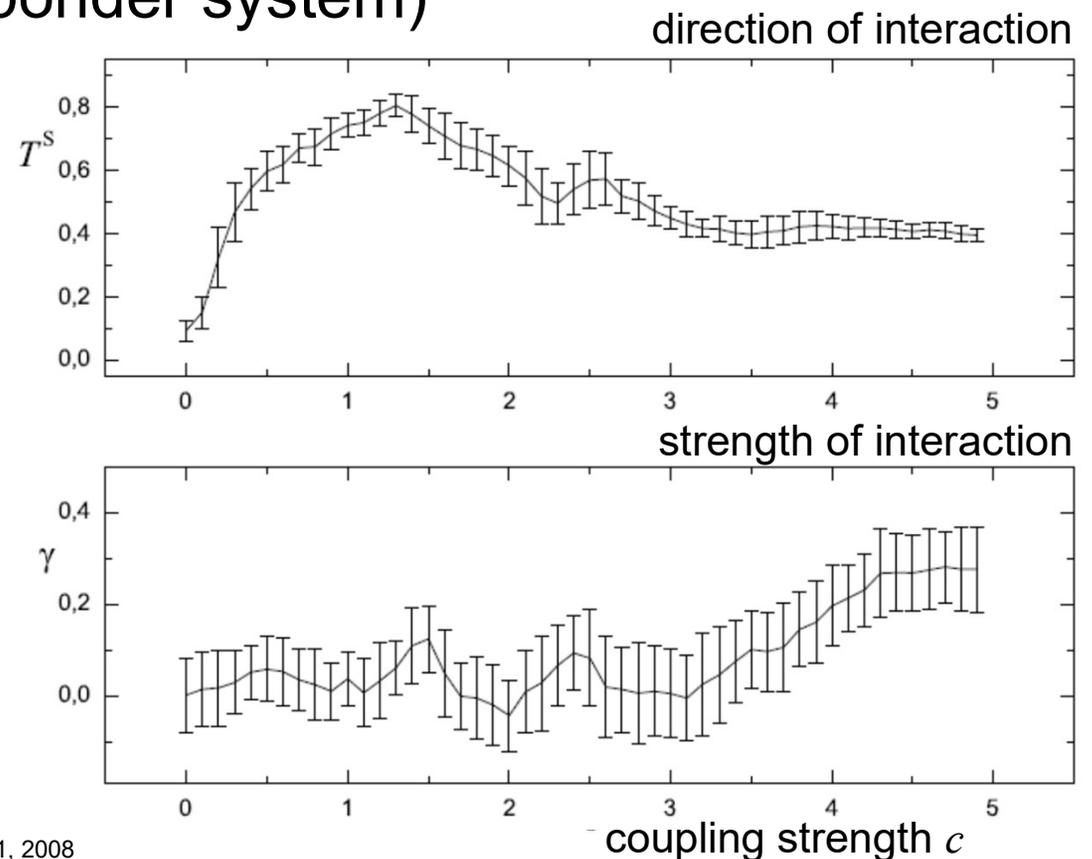
diffusively coupled Rössler-Lorenz oscillators  
(100 realizations of driver-responder system)

$$\begin{aligned}\dot{x}^R &= -\Omega^R(y^R - z^R) \\ \dot{y}^R &= \Omega^R(x^R + 0.2y^R) \\ \dot{z}^R &= \Omega^R(0.2 + z^R(x^R - 5.7))\end{aligned}$$

$$\begin{aligned}\dot{x}^L &= 10(y^L - x^L) \\ \dot{y}^L &= \Omega^L x^L - y^L - x^L z^L + c(y^R)^2 \\ \dot{z}^L &= x^L y^L - \frac{8}{3} z^L\end{aligned}$$

$$\Omega^R \in \mathcal{N}(6, 0.1)$$

$$\Omega^L \in \mathcal{N}(28, 1)$$



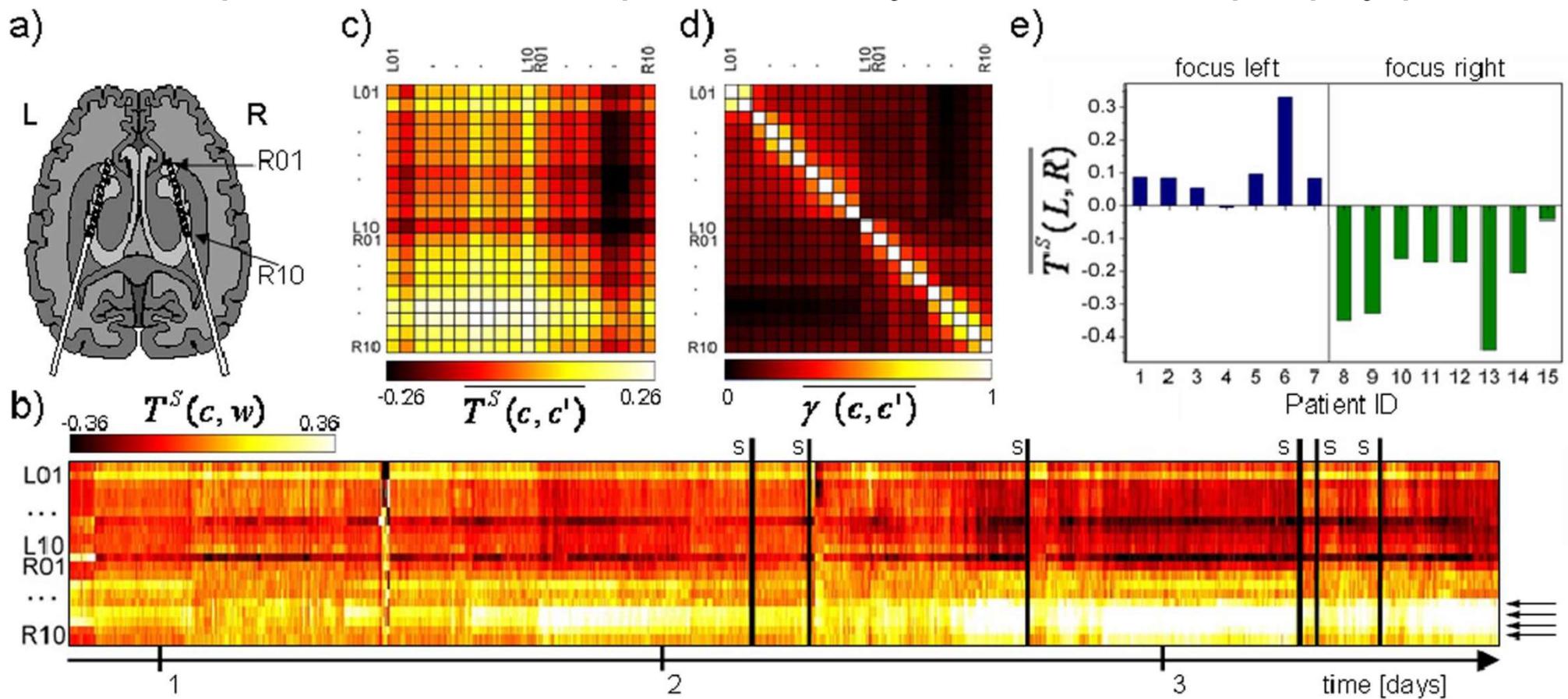
measuring interactions

**strength and direction of interaction**

driver-responder relationships in EEG dynamics from epilepsy patients

information-theory

**an example**



## **measuring interactions**

## **information-theory**

### ***strength and direction of interaction***

permutation-entropy-based estimators

### advantages

- easy-to-use, fast-to-calculate
- high robustness against noise (symbolization)

### disadvantages

- symbolization may lead to loss of information
- require appropriate choice of embedding parameter
- choice of window-size, finiteness of available symbols
- “faster” system (eigen-frequency, noise) → driver  
(need reliable surrogate test for directionality)
- may be fooled by (unobserved) third system