

Measuring Interactions from Time Series

phase-based techniques

measuring interactions

phase

basic idea: interaction \Leftrightarrow phase dynamics \Leftrightarrow synchronization

- the “stronger” the interaction, the more similar are the phases
- interaction-induced perturbation of phases indexes directionality

neglect amplitude information

phase \Leftrightarrow nonlinearity \rightarrow interesting for chaotic systems

need to derive phase from time series

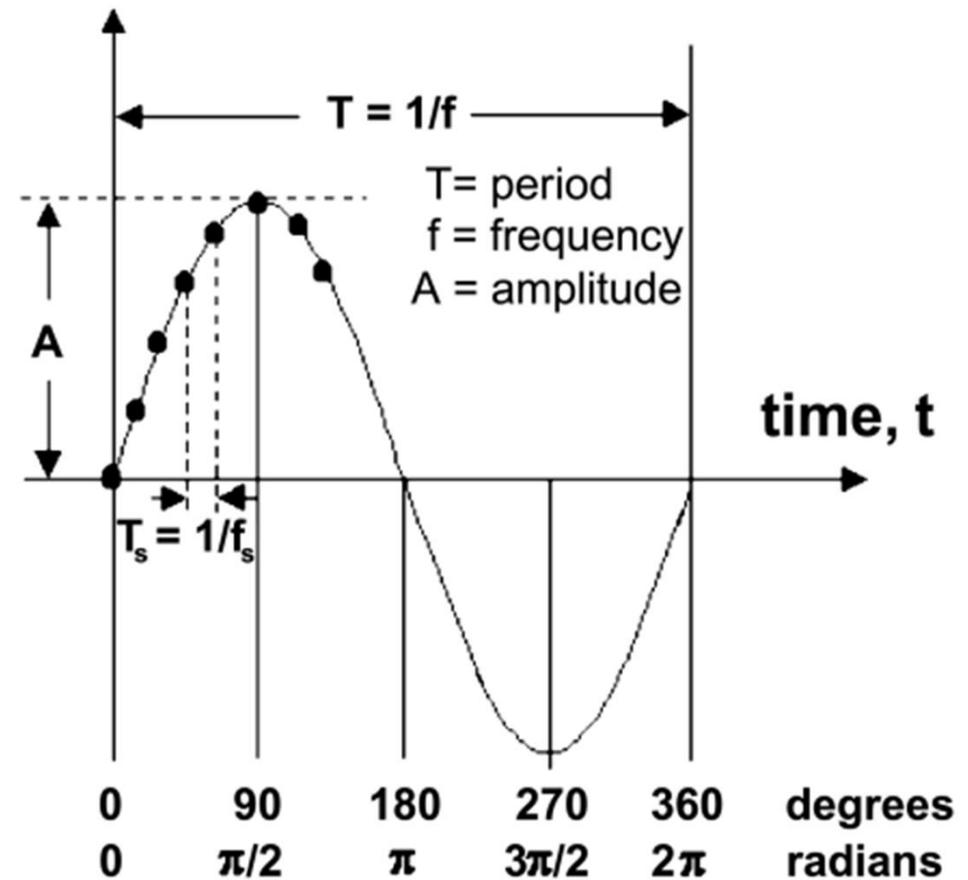
measuring interactions

phase

the phase of a periodic function of some real variable t is the relative value of that variable within the span of each full period

phase is typically expressed as an angle $\phi(t)$

$\phi(t) \in [0^\circ, 360^\circ)$ or $\phi(t) \in [0, 2\pi)$



measuring interactions

phase

phase synchronization

classical definition (“phase locking”)

“adjustment of rhythms of oscillating objects due to a weak interaction”

$$n\phi_1(t) - m\phi_2(t) = \text{const}; \quad (n, m) \in \mathbb{N}$$

extension for noisy and chaotic systems (“weak phase locking”):

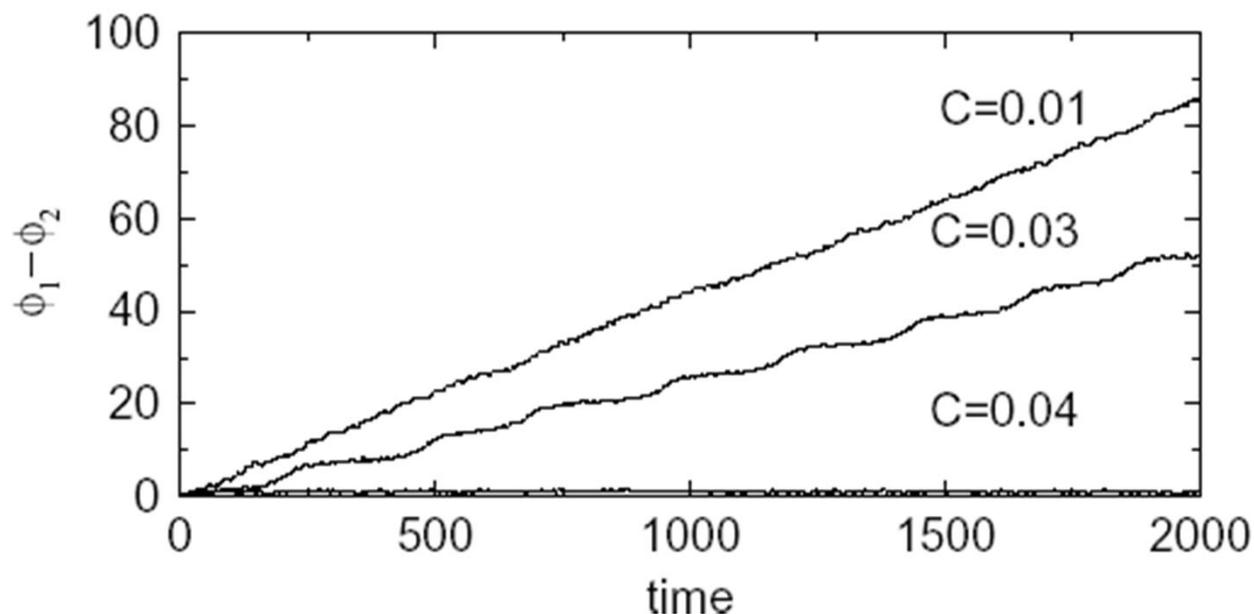
“induction of relationships between the functionals of two processes due to an interaction”

$$n\phi_1(t) - m\phi_2(t) < \text{const}; \quad (n, m) \in \mathbb{N}$$

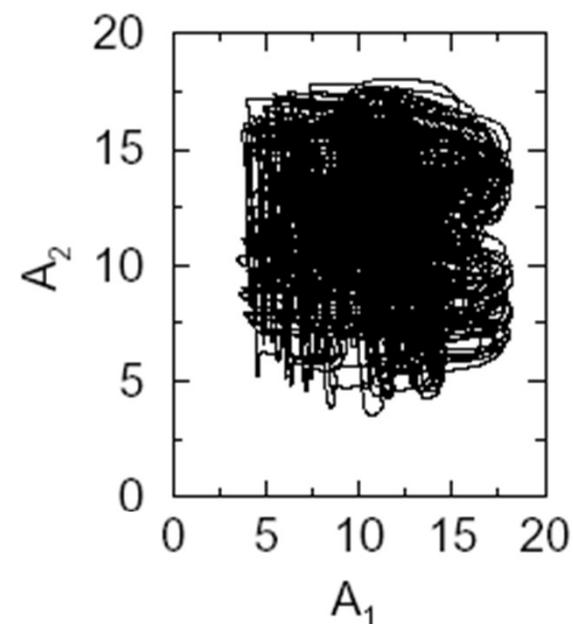
measuring interactions**phase****phase synchronization of chaotic oscillators**

example: non-identical uni-directionally coupled Rössler oscillators
(C = coupling strength)

adjustment of phases
(from phase-slips to phase-locking)



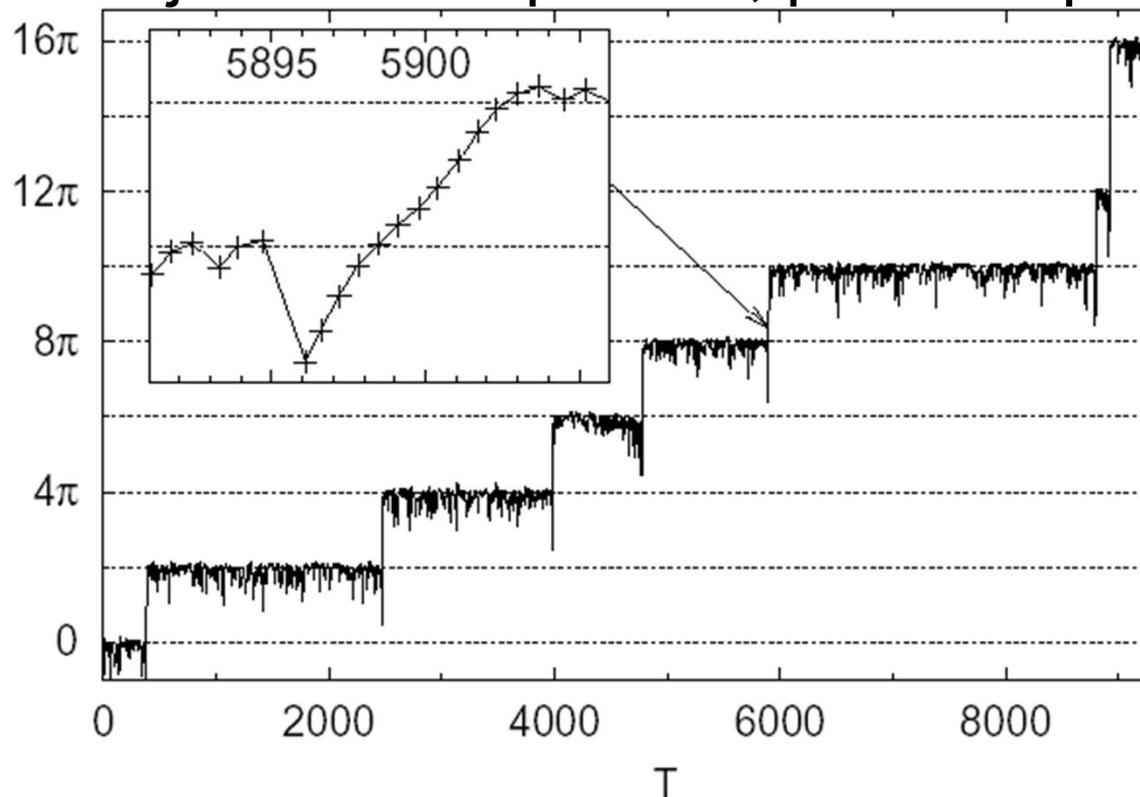
amplitudes remain
uncorrelated and chaotic



measuring interactions**phase****phase synchronization of chaotic oscillators**

example: non-identical uni-directionally coupled Rössler oscillators
(C = coupling strength)

adjustment of phases; phase-slips



*devil's
staircase*

measuring interactions**deriving phases from time series**

given: time series \mathbf{v} of some observable \mathbf{x} and

time series \mathbf{w} of some observable \mathbf{y}

and

given some reference time point (e.g. $t_0 = 0$)

(holds for strictly periodic functions, triggered data, impulse responses, transfer functions)

→ define phase relative to t_0

let $v(t) = A(t) \cos(\phi(t_0 + t))$ (analogously for $w(t)$)

with $z(t) = A(t) \exp(i\phi(t_0 + t))$, we have:

$$v(t) = \Re(z(t))$$

$$\phi(t) = \arctan \left(\frac{\Re(z(t))}{\Im(z(t))} \right)$$

$$A(t) = \sqrt{(\Re(z(t)))^2 + (\Im(z(t)))^2}$$

derive imaginary part
with e.g. Fourier transform

measuring interactions

deriving phases from time series

given: time series \mathbf{v} of some observable \mathbf{x} and
time series \mathbf{w} of some observable \mathbf{y}

if no reference time point given
(arbitrary real-valued signals)

→ define phase using

- zero-crossings (or other marker-events; Rice, 1944)
- Hilbert-transform (Gabor, 1946; Panter 1965)
- (- wavelet-transform (Lachaux et al., 1999)*)

measuring interactions

deriving phases from time series

phases from zero-crossings

ansatz: successive zero-crossings correspond to completion of a period

- subtract mean value (*demeaning*) if necessary

- let t_k denote beginning of a period and t_{k+1} the next (e.g. via: $v^- \rightarrow 0$ or $v^+ \rightarrow 0$)

- derive phase with linear interpolation:

$$\phi(t) := \frac{t-t_k}{t_{k+1}-t_k} 2\pi + k2\pi; \quad \text{where } t_k \leq t < t_{k+1}$$

measuring interactions

deriving phases from time series

phases from zero-crossings

pros:

easy

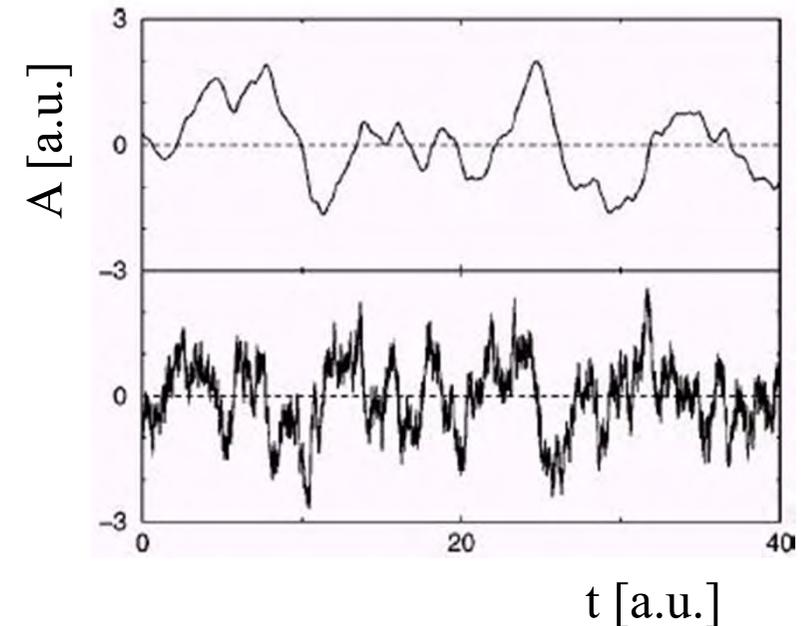
fast computation

cons:

requires some periodicity

requires smooth signals

extremely sensitive to noise



from: Callenbach et al., PRE 65, 051110, 2002

measuring interactions

deriving phases from time series

phases from Hilbert-transform

ansatz: define *instantaneous* phase $\phi(t)$ using the analytic signal:

$$z(t) = v(t) + i\tilde{v}(t)$$

Hilbert-transform \mathcal{HT} is defined as:

$$\mathcal{HT}(v(t)) = \tilde{v}(t) := v(t) * \frac{1}{\pi t} = \frac{1}{\pi} \text{p.v.} \int_{-\infty}^{+\infty} \frac{v(\tau)}{t - \tau} d\tau$$

p.v. = Cauchy principal value

measuring interactions

deriving phases from time series

phases from Hilbert-transform

representation in frequency domain:

(use Fourier transform \mathcal{FT} and convolution theorem)

$$\text{with } \mathcal{FT}\left(\frac{1}{\pi t}\right) = -i \operatorname{sign}(\omega) = \begin{cases} +i : & \text{if } \omega < 0 \\ 0 : & \text{if } \omega = 0 \\ -i : & \text{if } \omega > 0 \end{cases}$$

$$\text{we have: } \tilde{v}(t) = \mathcal{FT}^{-1} [\mathcal{FT}(v(t)) (-i) \operatorname{sign}(\omega)]$$

and:

$$\phi(t) = \arctan \frac{\tilde{v}(t)}{v(t)} \quad \text{instantaneous phase (possibly phase unfolding required)}$$

$$\omega(t) = \dot{\phi}(t) \quad \text{instantaneous frequency}$$

spectral power remains unchanged; phases of Fourier spectrum shifted by $\pi/2$

measuring interactions

deriving phases from time series

phases from Hilbert-transform

basic example: strongly periodic oscillation

given $v(t) = A \cos(\omega t)$; with $(A, \omega) = \text{const}$

$\mathcal{HT}(v(t)) := \tilde{v}(t) = -A \sin(\omega t)$

$\Rightarrow \phi(t) = \arctan\left(-\frac{\sin \omega t}{\cos \omega t}\right) = -\omega t$

sign: historical reasons

measuring interactions

deriving phases from time series

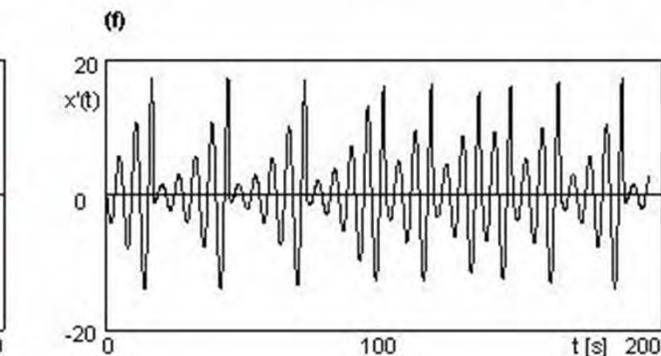
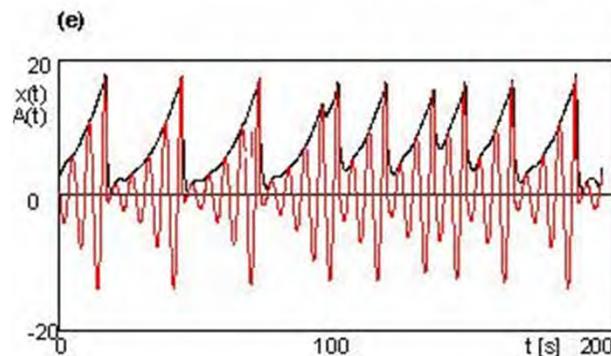
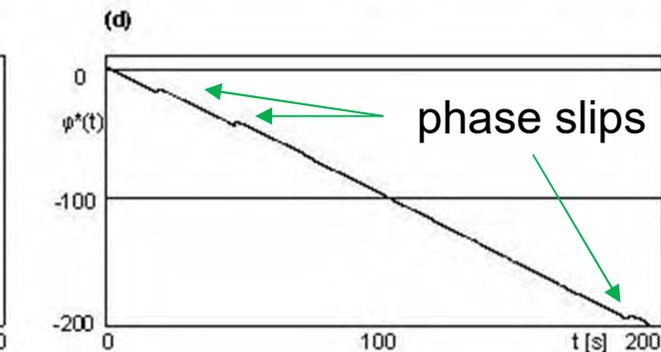
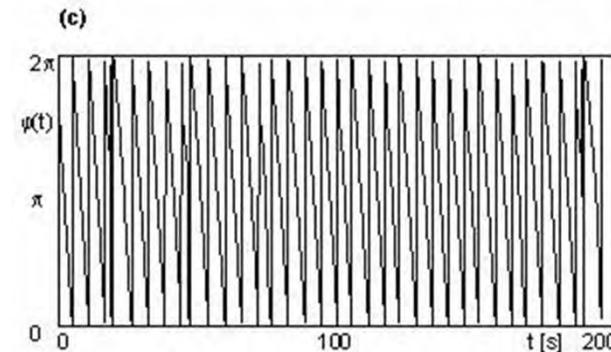
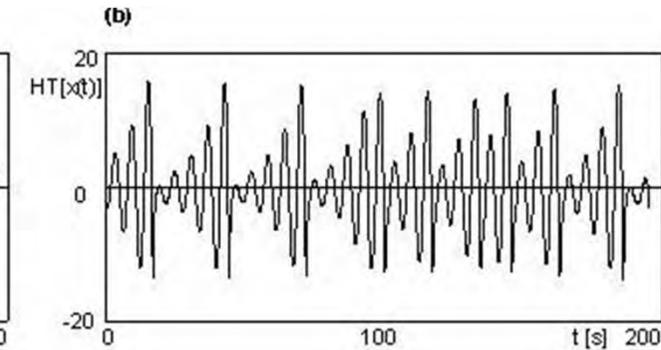
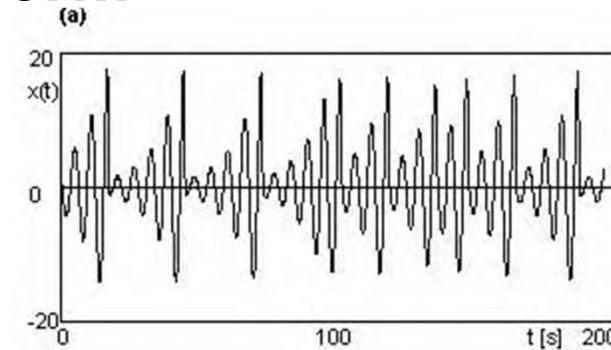
phases from Hilbert-transform

example: x -component of Rössler oscillator

$$\dot{x} = -0.89y - z$$

$$\dot{y} = x + 0.165y$$

$$\dot{z} = 0.2 + z(x - 10)$$



measuring interactions

deriving phases from time series

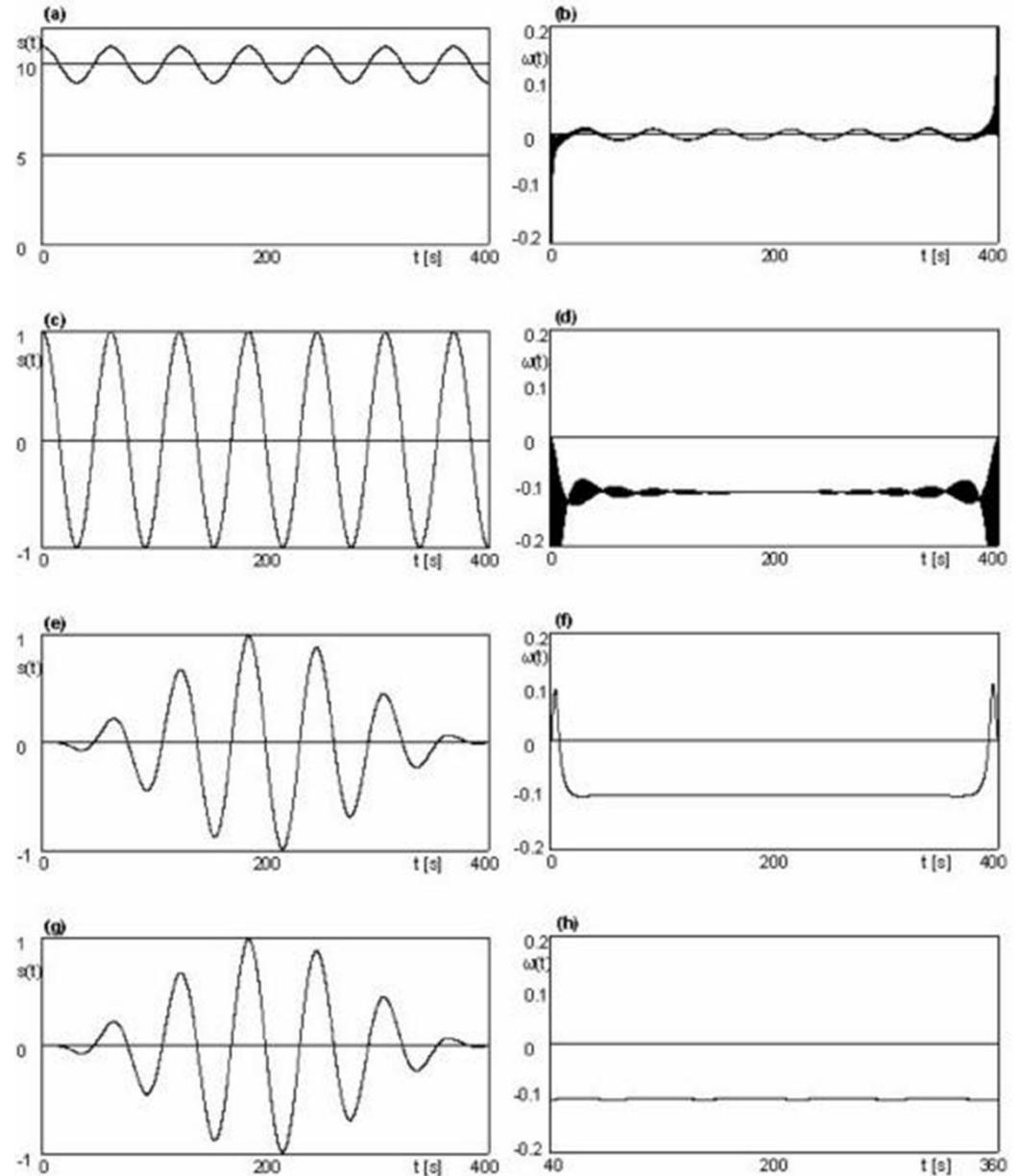
phases from Hilbert-transform

time series analysis: how to

- some periodicity required
- duration of signal: sampling theorem; about 20 data points/period;
stationarity (at least approximate)
- offsets not taken into account, needs demeaning (subtract mean)
- if you use FFT on finite time series:
 - requires trimming/tapering
 - tapering can lead to distortions
- unfolding of phases required
- computational speed: $O(N \log(N))$

measuring interactions
phases from Hilbert-transform
time series analysis: how to

deriving phases from time series



measuring interactions**strength of interaction**

- given phase time series from time series ν and w
- phase synchronization if phase difference time series bounded:

$$\Delta\phi_{\nu w}(t) := n\phi_{\nu}(t) - m\phi_w(t) \leq \text{const}; \quad \forall t$$

- if phases derived from Hilbert transform: any (n, m)
- if phases derived from zero-crossings: $n = m = 1$
- need to test boundedness

measuring interactions

strength of interaction

statistical ansatz: ***mean phase coherence****

- phase differences limited to $(0, 2\pi]$ (due to arcus tangens)
 → natural circularity → circular statistics**
- estimate moments of “*circular distributions*” by transforming the phase differences onto unit circle in complex plane

$$\Delta\phi_{vw}(t) = n\phi_v(t) - m\phi_w(t) \leq \text{const}$$

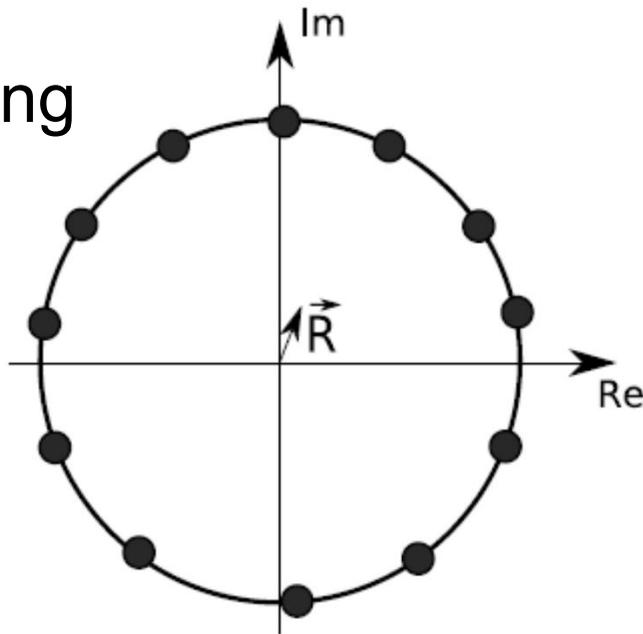
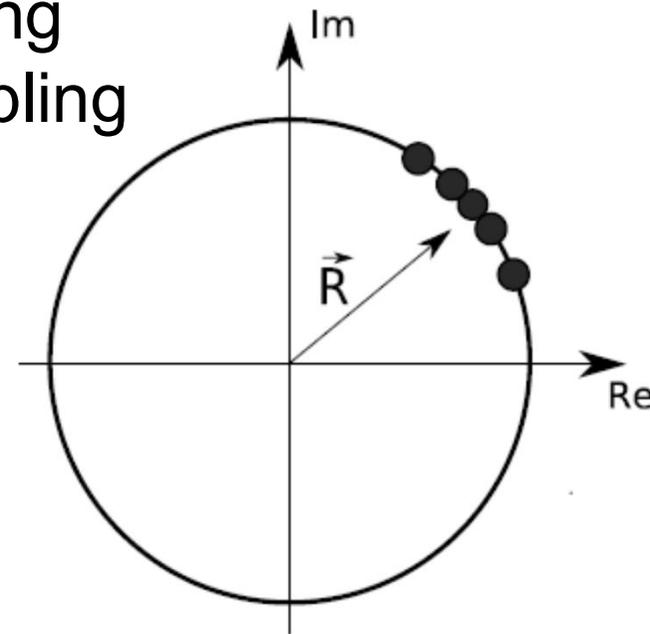
$$z(t) = \cos(\Delta\phi_{vw}(t)) + i \sin(\Delta\phi_{vw}(t)) = \exp i(\Delta\phi_{vw}(t))$$

$$Z = \frac{1}{T} \sum_{t=1}^T z(t)$$

$$R := |Z| = \sqrt{(\Re Z)^2 + (\Im Z)^2}$$

*M Hoke, K Lehnertz, C Pantev, B Lütkenhöner. Spatiotemporal aspects of synergetic processes in the auditory cortex as revealed by magnetoencephalogram, in: E. Basar, T.H. Bullock (Eds.), Series in Brain Dynamics, Vol. 2, Springer, Berlin, 1989. F Mormann, K Lehnertz, P David, CE Elger. Mean phase coherence as a measure for phase synchronization and its application to the EEG of epilepsy patients. Physica D, 144, 358, 2000

** e.g. KV Mardia, P Jupp. *Directional Statistics*, John Wiley and Sons Ltd., 2000

measuring interactionsstatistical ansatz: ***mean phase coherence*****strength of interaction**weak
couplingstrong
coupling

$$R \in [0,1]$$

 $R = 1$ complete phase synchronization (full phase locking) $R = 0$ no phase synchronization

$$S = 1 - R \text{ (circular variance)}$$

measuring interactions

statistical ansatz: ***mean phase coherence***

diffusively coupled oscillators
(with eigen-frequencies Ω_v and Ω_w)

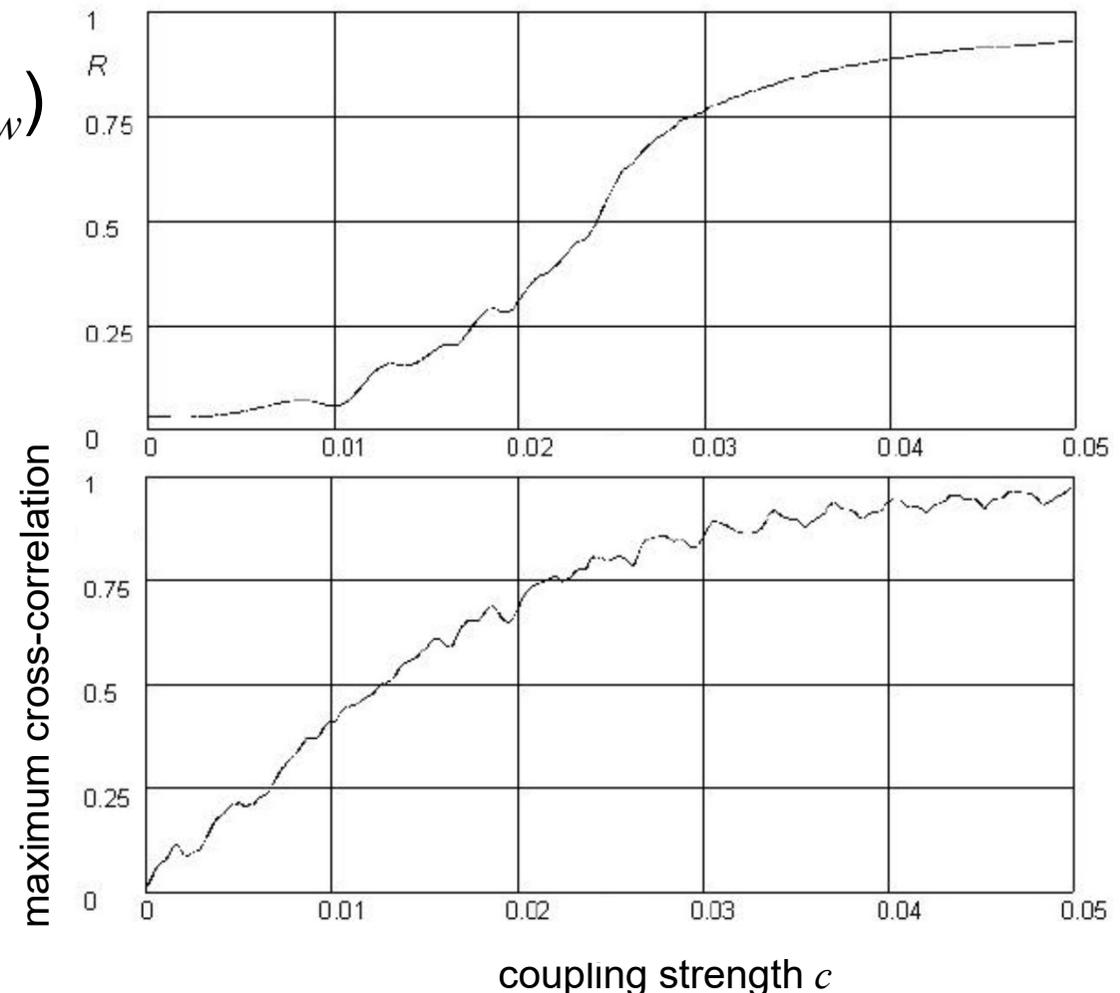
$$\ddot{\mathbf{v}} = -\Omega_v \mathbf{v} + c(\mathbf{w} - \mathbf{v})$$

$$\ddot{\mathbf{w}} = -\Omega_w \mathbf{w} + c(\mathbf{v} - \mathbf{w})$$

single realization

strength of interaction

examples



measuring interactions

statistical ansatz: *mean phase coherence*

diffusively coupled

Lorenz oscillators

$$\dot{x}_{1,2} = -\frac{8}{3}x_{1,2} + y_{1,2}z_{1,2} + c(x_{2,1} - x_{1,2})$$

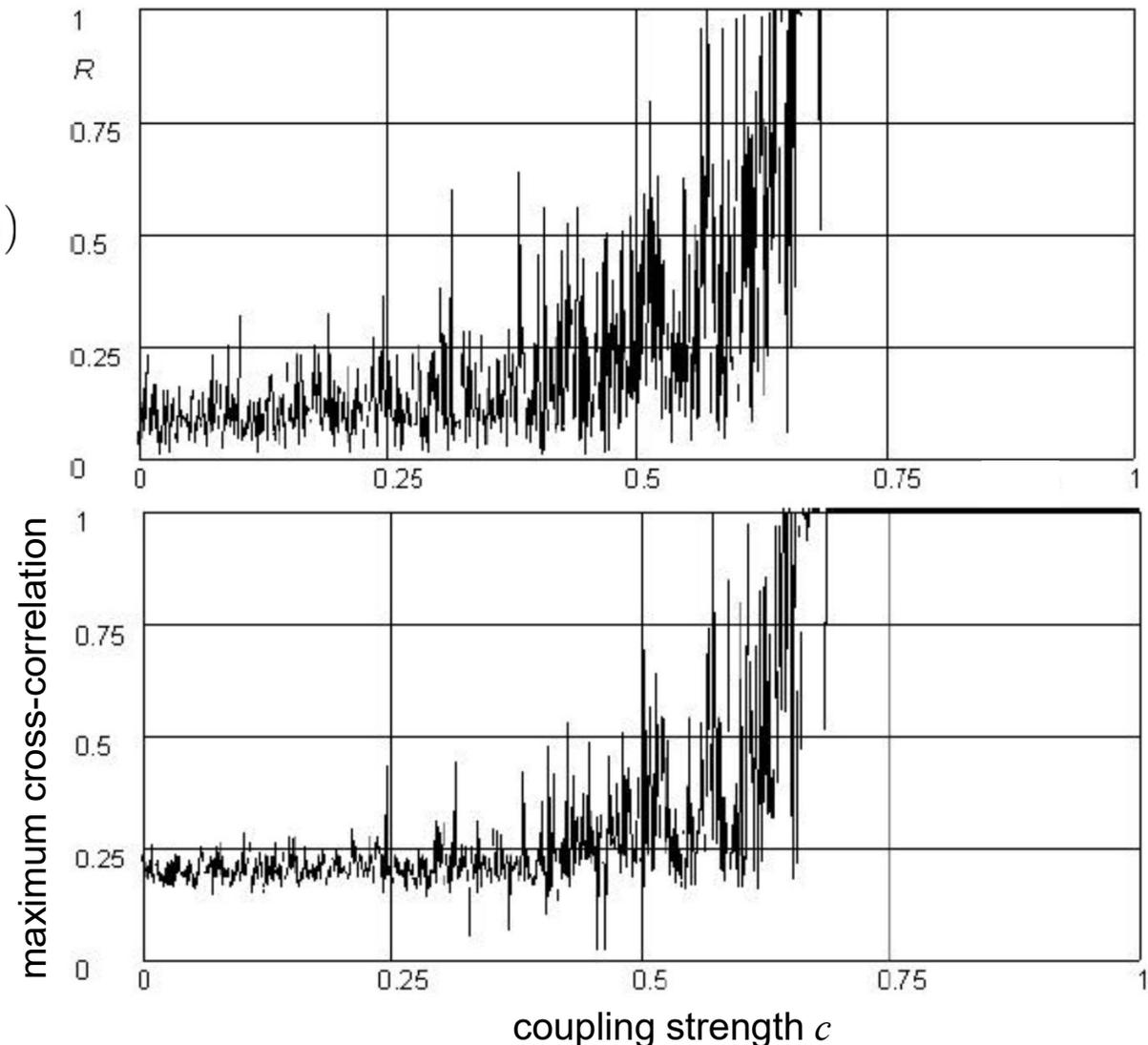
$$\dot{y}_{1,2} = R_{1,2}z_{1,2} - y_{1,2} - x_{1,2}z_{1,2}$$

$$\dot{z}_{1,2} = 10(y_{1,2} - z_{1,2})$$

$$R_1 = 28; R_2 = 28.00001$$

single realization

strength of interaction

examples

measuring interactions

statistical ansatz: *mean phase coherence*

strength of interaction

*examples*diffusively coupled
Rössler oscillators

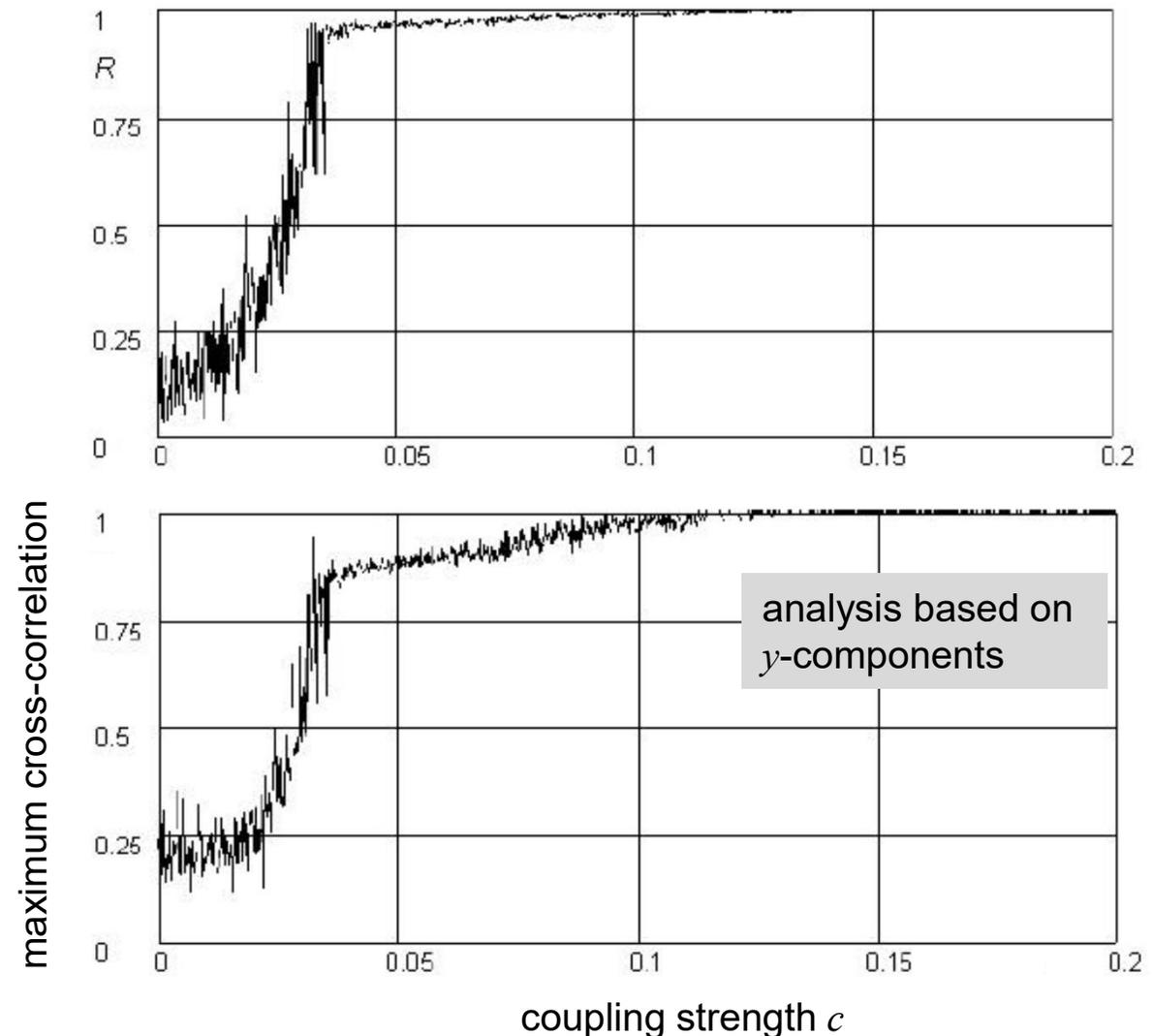
$$\dot{x}_{1,2} = -\Omega_{1,2}y_{1,2} - z_{1,2} + c(x_{2,1} - x_{1,2})$$

$$\dot{y}_{1,2} = \Omega_{1,2}x_{1,2} + 0.165y_{1,2}$$

$$\dot{z}_{1,2} = 0.2 + z_{1,2}(x_{1,2} - 10)$$

$$\Omega_1 = 0.89; \Omega_2 = 0.85$$

single realization



measuring interactions

statistical ansatz: *mean phase coherence*

diffusively coupled

Lorenz oscillators

$$\dot{x}_{1,2} = -\frac{8}{3}x_{1,2} + y_{1,2}z_{1,2} + c(x_{2,1} - x_{1,2})$$

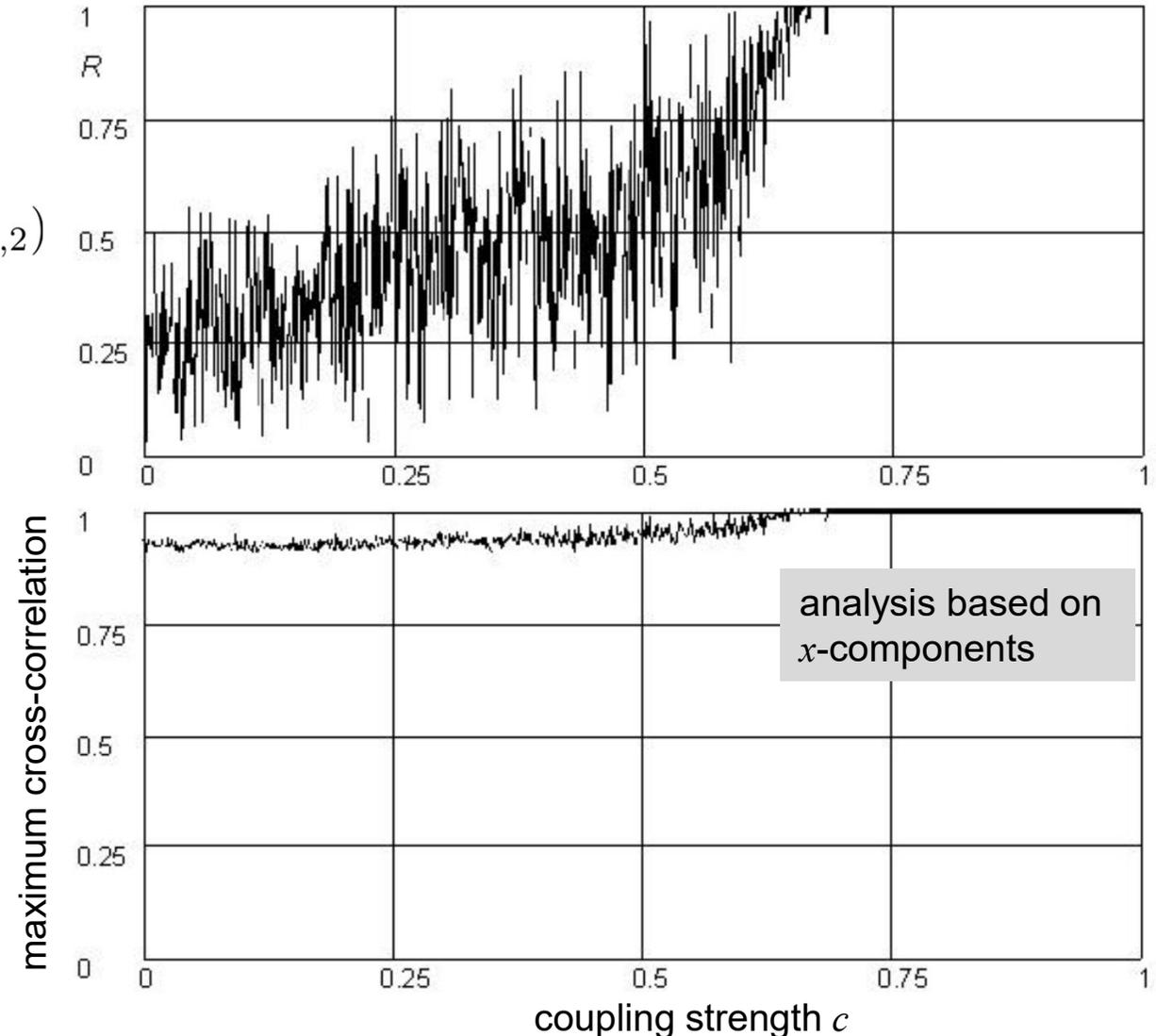
$$\dot{y}_{1,2} = R_{1,2}z_{1,2} - y_{1,2} - x_{1,2}z_{1,2}$$

$$\dot{z}_{1,2} = 10(y_{1,2} - z_{1,2})$$

$$R_1 = 28; R_2 = 28.00001$$

single realization

strength of interaction

examples

measuring interactions

statistical ansatz: *mean phase coherence*

robustness against noise for diffusively coupled oscillators

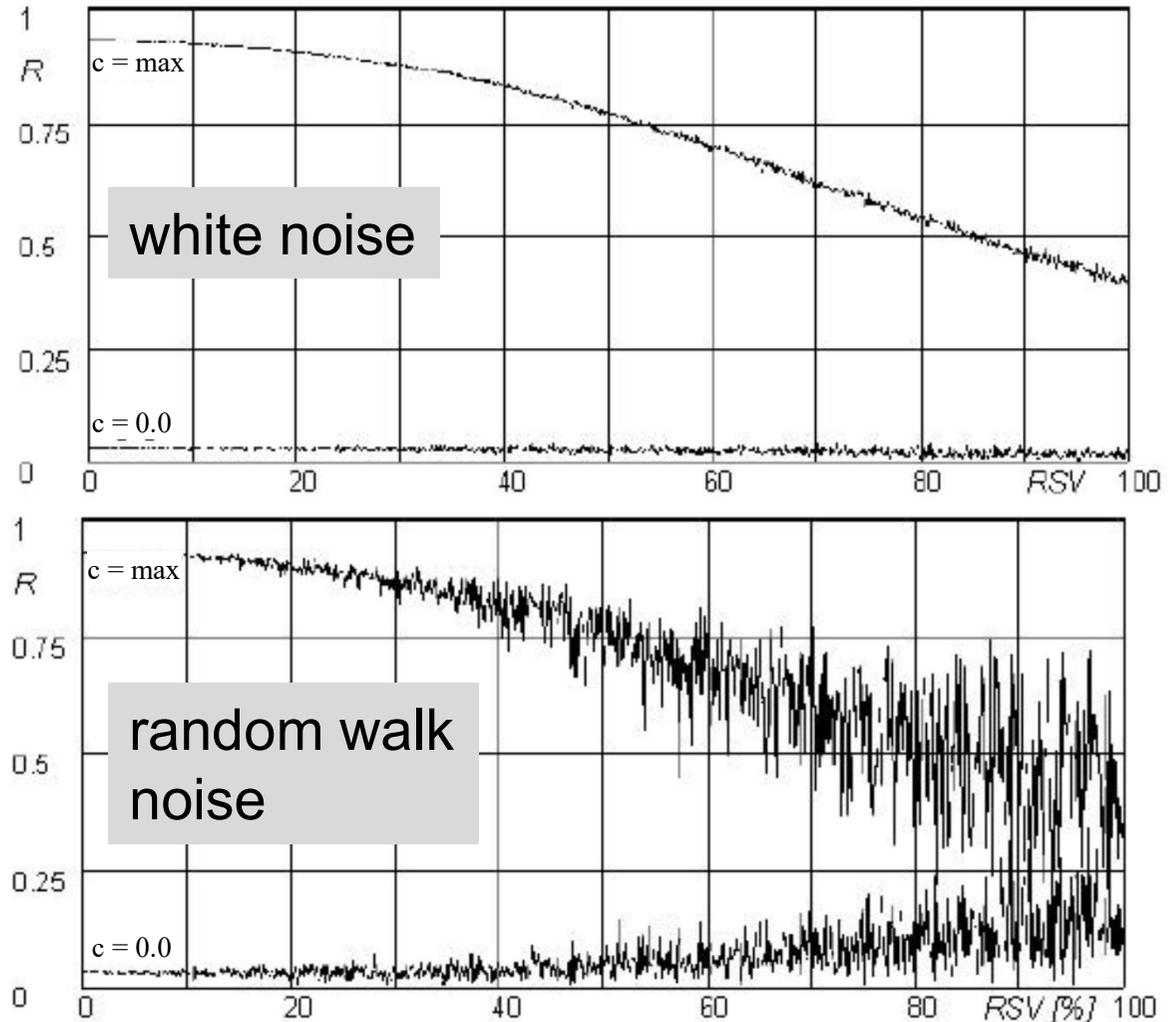
no coupling vs. maximum coupling

single realization

$$RSV = \frac{\sigma_{\text{noise}}}{\sigma_{\text{signal}}}$$

strength of interaction

examples



measuring interactions

statistical ansatz: *mean phase coherence*

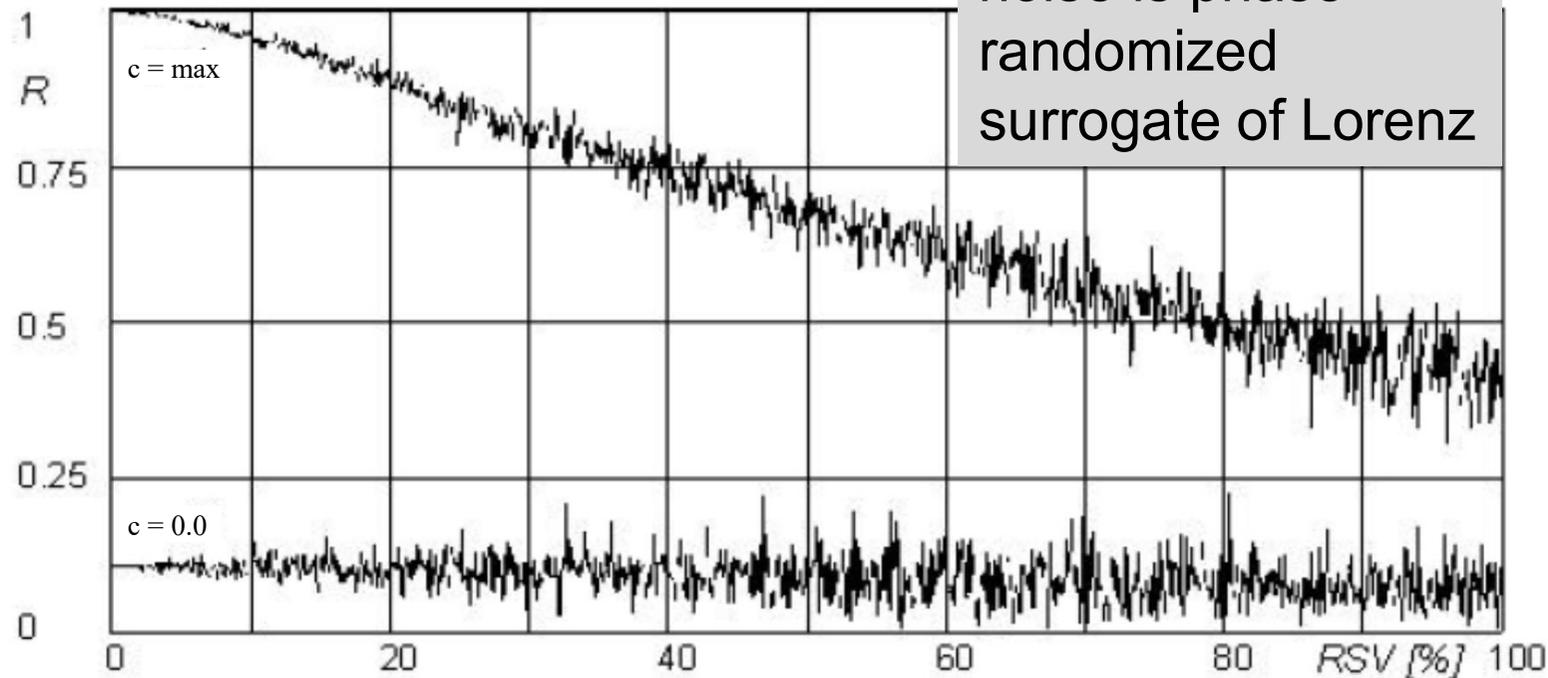
robustness against noise for
diffusively coupled Lorenz
oscillators (*y*-component)

no coupling vs.
maximum coupling

single realization

strength of interaction

examples



$$RSV = \frac{\sigma_{\text{noise}}}{\sigma_{\text{signal}}}$$

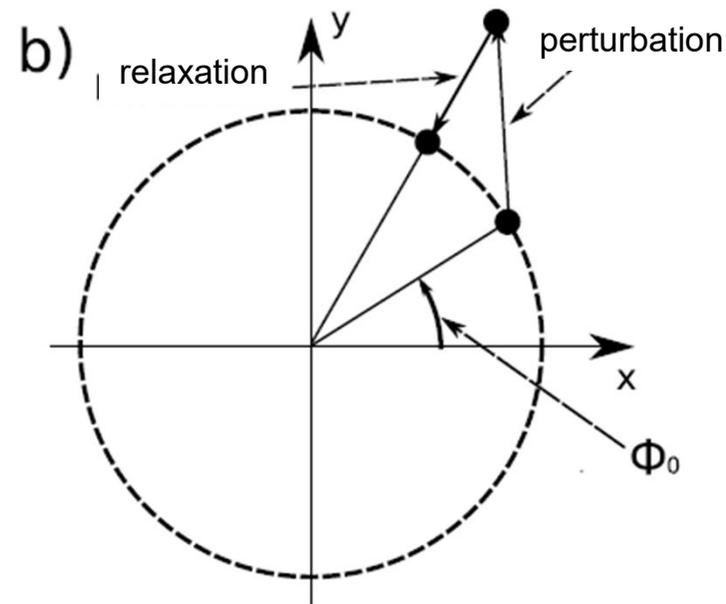
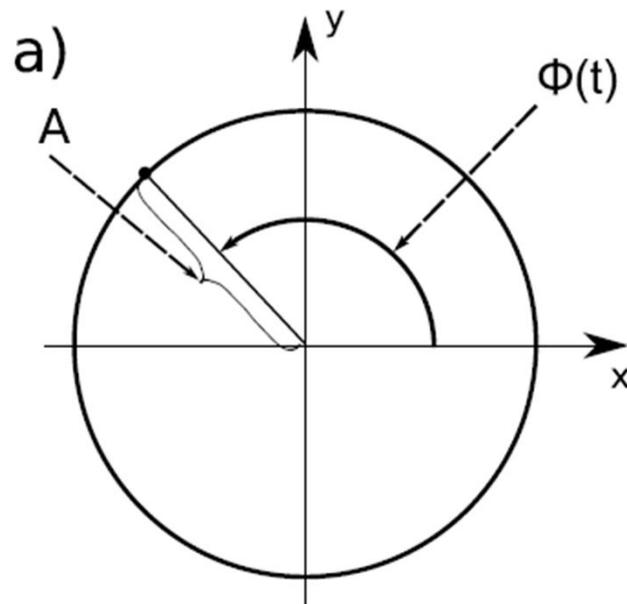
measuring interactions

strength of interaction

- other approaches (based on information theory; Tass et al., 1998)
 - index based on Shannon entropy
 - index based on conditional probability
- different approaches yield similar findings (application dependent)
- mean phase coherence most robust, easiest to estimate, wide applicability
- mean phase coherence and related approaches are symmetric (under exchange of ν and w)
 - can not indicate direction of interaction

measuring interactions

- given phase time series from time series ν and w
- observation: weak interaction induces perturbation of phases dynamics (perturbation of amplitudes can be neglected)

direction of interaction

- need a characterization of mutual perturbations of phase dynamics

measuring interactions**direction of interaction**

from simplified phase model to ***cross dependencies***
(evolution map approach*)

- assumption: weakly coupled, self-sustained oscillators

$$\dot{\phi}_1(t) = \omega_1 + \kappa_1 f_1(\phi_1(t), \phi_2(t)) + \xi_1(t)$$

$$\dot{\phi}_2(t) = \omega_2 + \kappa_2 f_2(\phi_2(t), \phi_1(t)) + \xi_2(t)$$

$f_{1,2}(\phi_{1,2})$ are coupling functions

$\kappa_{1,2}$ are damping constants

stochastic components $\xi_{1,2}$ for noisy or chaotic oscillators

weak coupling if $\kappa_{1,2} f_{1,2} \ll \omega_{1,2}$

measuring interactions

direction of interaction

from simplified phase model to ***cross dependencies***

- define cross dependencies $d^{(1,2)}$

$$c_{1,2}^2 := \left\langle \left(\frac{\partial \dot{\phi}_{1,2}}{\partial \phi_{2,1}} \right)^2 \right\rangle = \kappa_{1,2} \left\langle \left(\frac{\partial f_{1,2}}{\partial \phi_{2,1}} \right)^2 \right\rangle$$

where $\langle (\cdot) \rangle = \int \int_0^{2\pi} (\cdot) d\phi_{1,2} d\phi_{2,1}$

$$d^{(1,2)} := \frac{c_2 - c_1}{c_1 + c_2} \quad \text{with } d^{(1,2)} \in [-1, 1]$$

measuring interactions**direction of interaction**

from simplified phase model to ***cross dependencies***

- interpretation of cross dependencies $d^{(1,2)}$

$$d^{(1,2)} = \begin{cases} +1 : & \text{if system 1 drives system 1 (unidirectional coupling)} \\ 0 : & \text{no driving identifiable (symmetric bidir. coupling)} \\ -1 : & \text{if system 2 drives system 1 (unidirectional coupling)} \end{cases}$$

measuring interactions**direction of interaction**

from simplified phase model to ***cross dependencies***

- numerical estimation of cross dependencies $d^{(1,2)}$

define incremental phase time series

$$\Delta_{1,2}(k) = \phi_{1,2}(t_k + \tau) - \phi_{1,2}(t_k)$$

with the (noisy) mapping

$$\Delta_{1,2}(k) = \mathcal{F}_{1,2}(\phi_{1,2}(t_k), \phi_{2,1}(t_k)) + \xi(t_k)$$

approximate \mathcal{F} with Fourier series using least-squares fit

$$\begin{aligned} \Delta_{1,2}(k) &\stackrel{\text{min!}}{\approx} F_{1,2}(\phi_{1,2}(t_k), \phi_{2,1}(t_k)) \\ &= \sum_{m,n} a_{m,n}^{1,2} \cos(m\phi_{1,2} + n\phi_{2,1}) \\ &\quad + b_{m,n}^{1,2} \sin(m\phi_{1,2} + n\phi_{2,1}) \end{aligned}$$

measuring interactions**direction of interaction**

from simplified phase model to ***cross dependencies***

- numerical estimation of cross dependencies $d^{(1,2)}$

with appropriately chosen orders of Fourier series, one finds:

$$c_{1,2}^2 = \left\langle \left(\frac{\partial \dot{\phi}_{1,2}}{\partial \phi_{2,1}} \right)^2 \right\rangle = 2\pi^2 \sum_{m,n} n^2 \left((a_{m,n}^{1,2})^2 + (b_{m,n}^{1,2})^2 \right)$$

note that the least-squares fit moderately reduces noise

measuring interactions

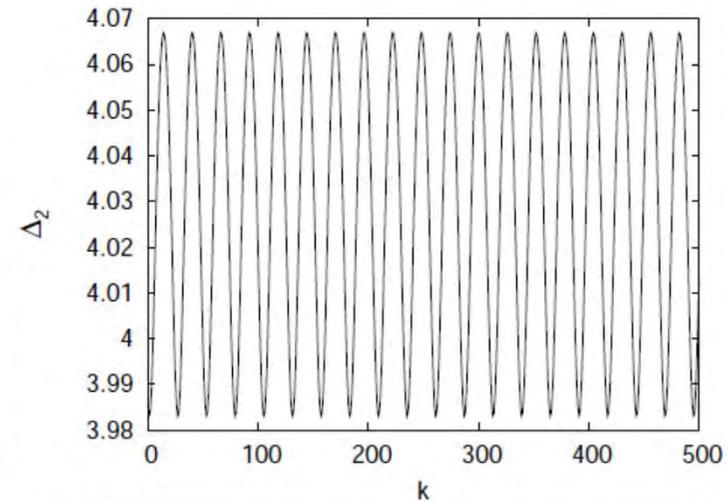
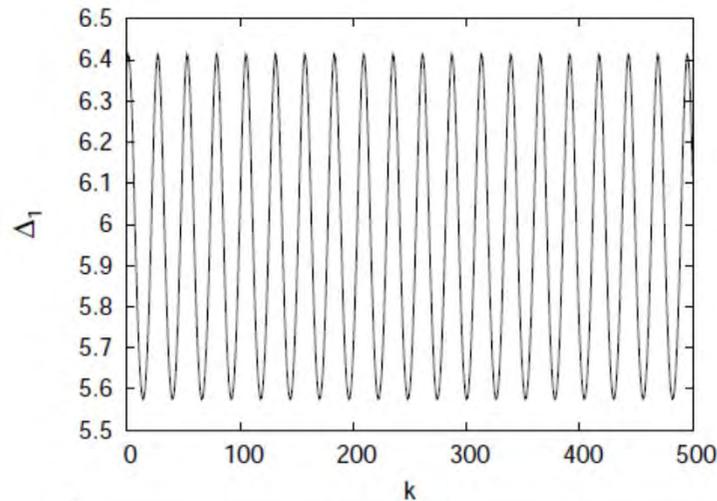
cross dependencies

$$\dot{\phi}_{1,2} = \omega_{1,2} + \kappa_{1,2} \sin(\phi_{1,2} - \phi_{2,1}) + D\xi_{1,2}$$

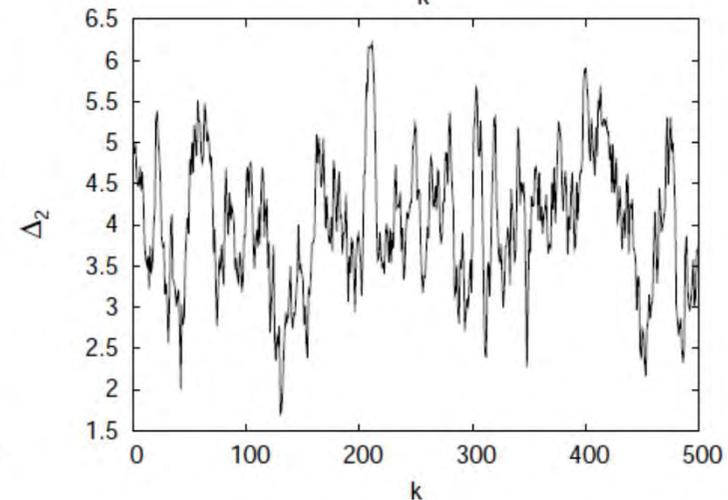
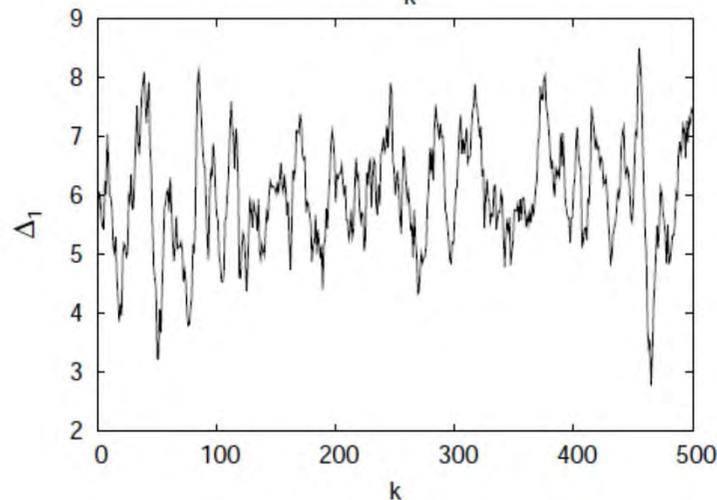
incremental
phase
time series

direction of interaction

examples



$D = 0.0$



$D = 0.4$

measuring interactions

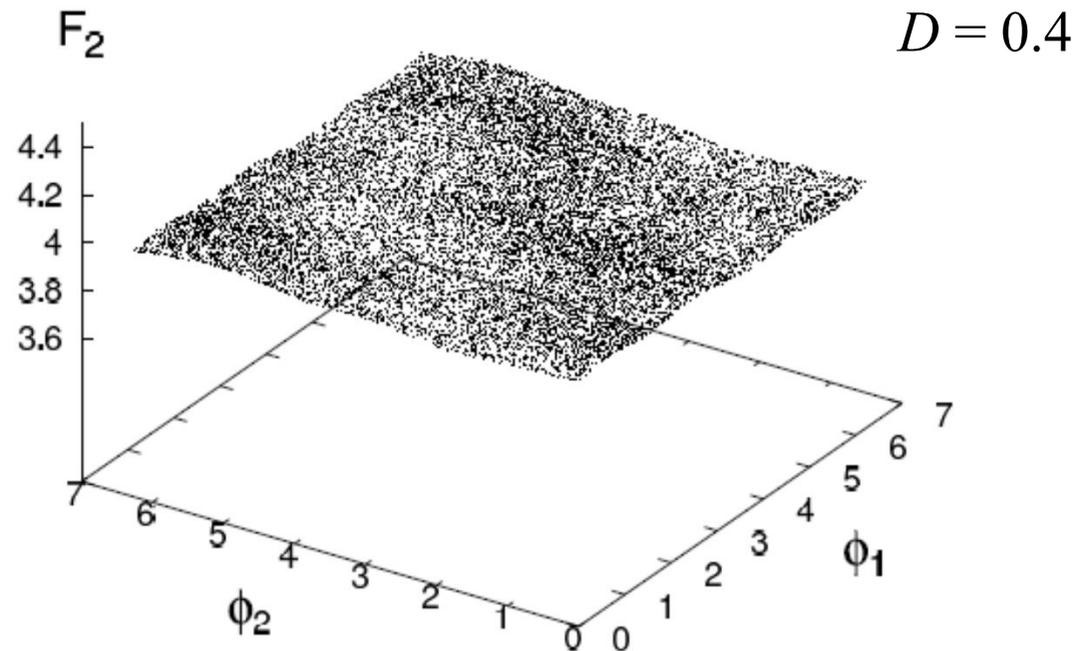
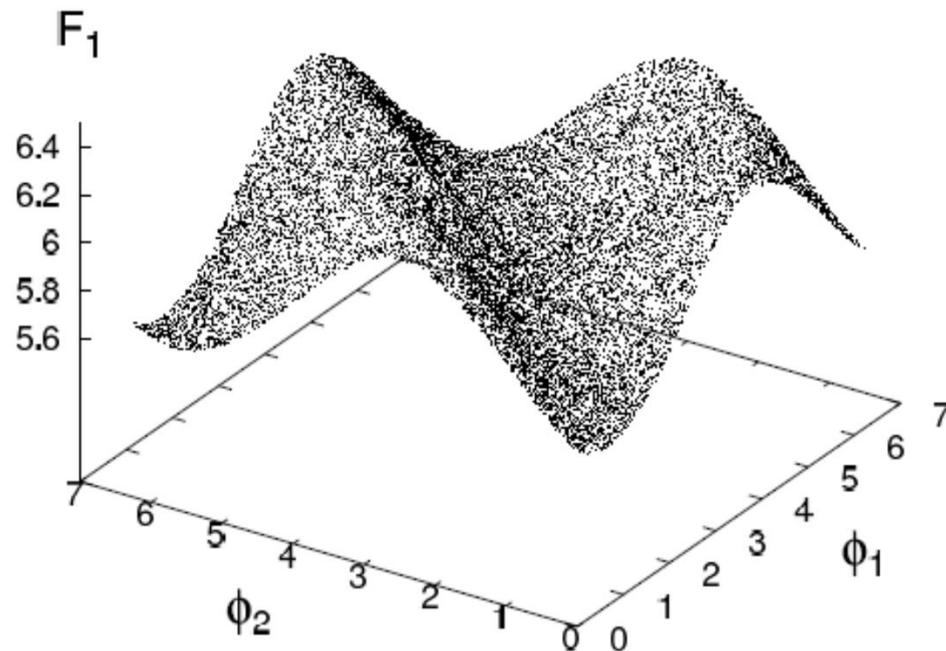
direction of interaction

cross dependencies

examples

$$\dot{\phi}_{1,2} = \omega_{1,2} + \kappa_{1,2} \sin(\phi_{1,2} - \phi_{2,1}) + D\xi_{1,2}$$

Fourier series

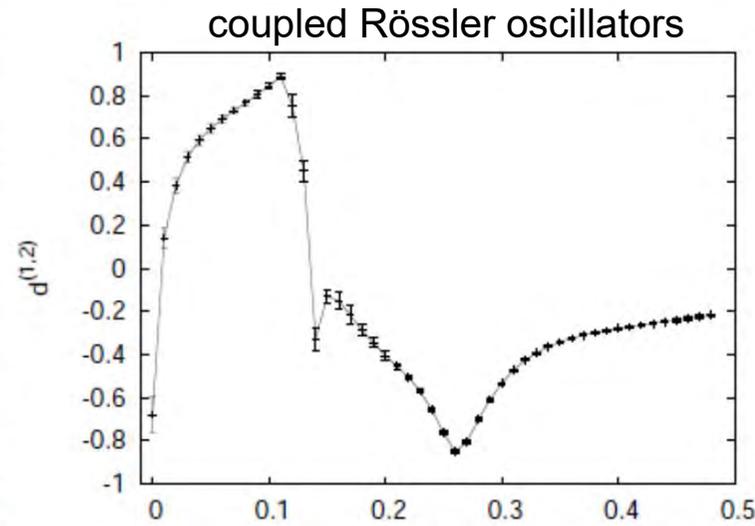
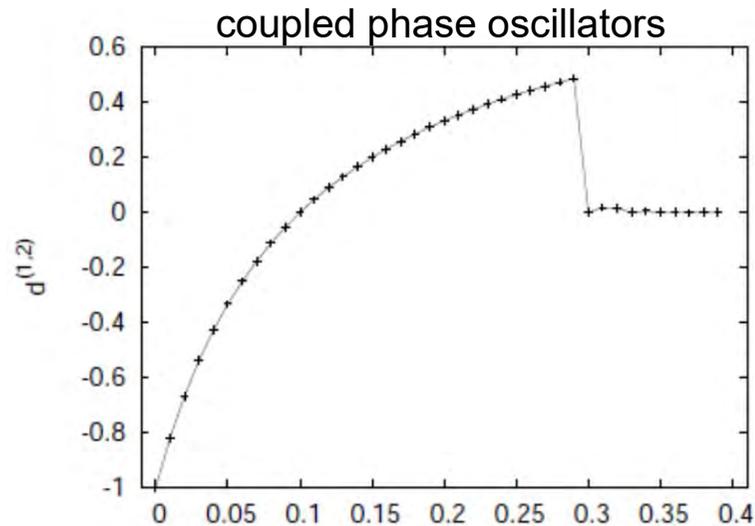


measuring interactions

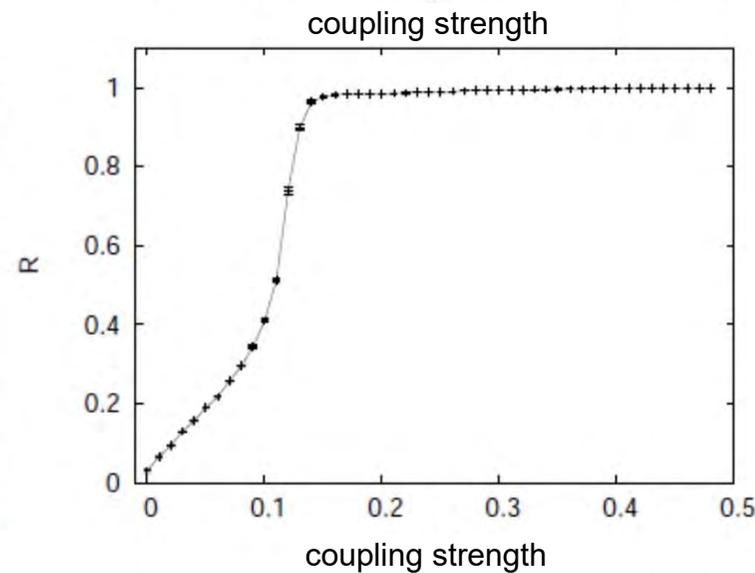
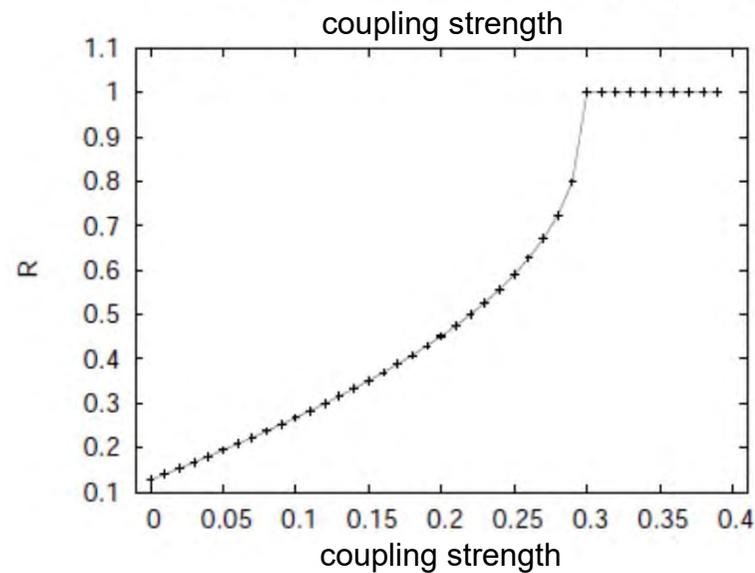
direction of interaction

cross dependencies

examples



cross dependencies



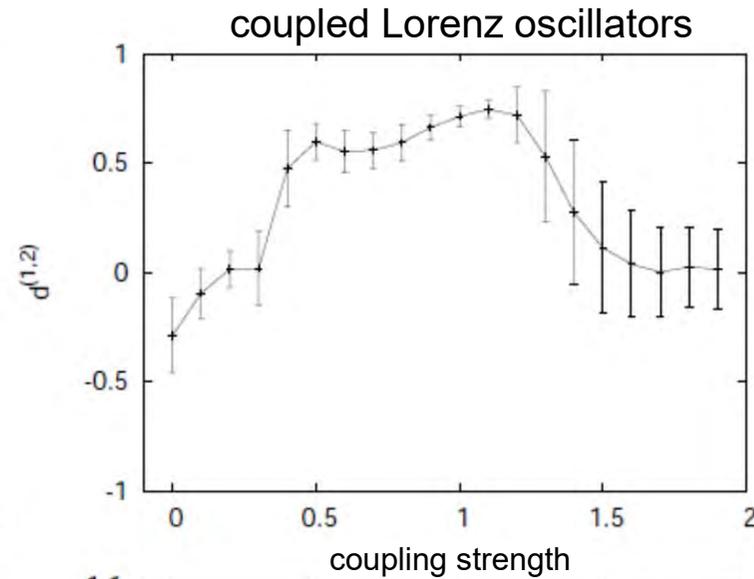
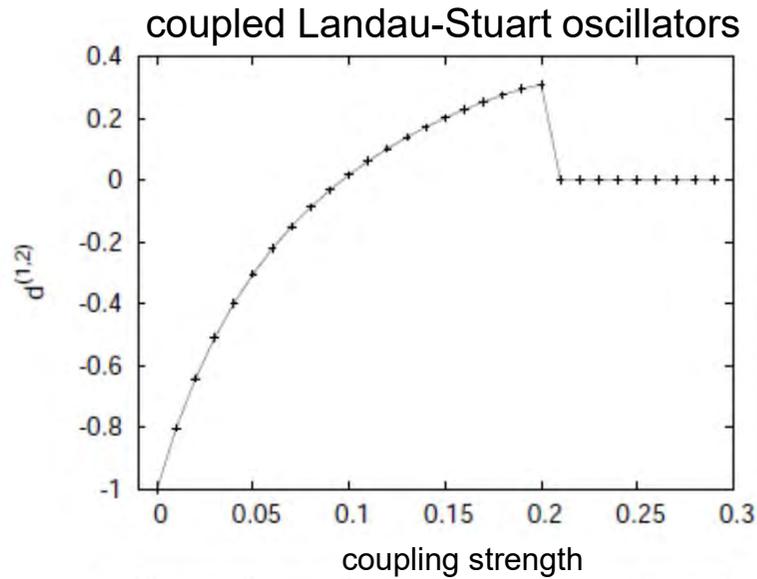
mean phase coherence

measuring interactions

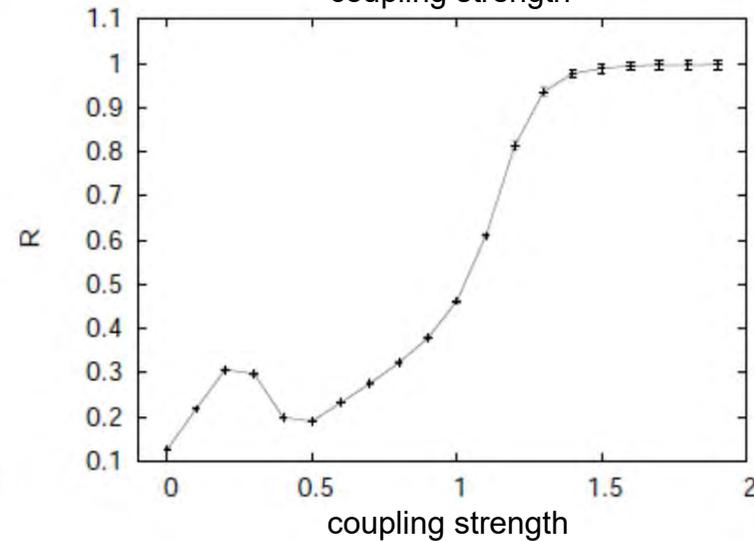
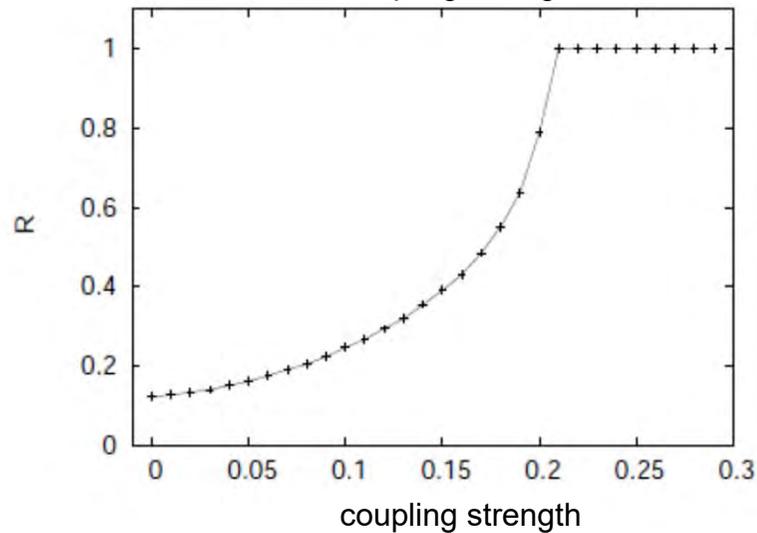
direction of interaction

cross dependencies

examples



cross dependencies



mean phase coherence

measuring interactions

cross dependencies

uncoupled(!)

Rössler oscillators

with different

eigen-frequencies

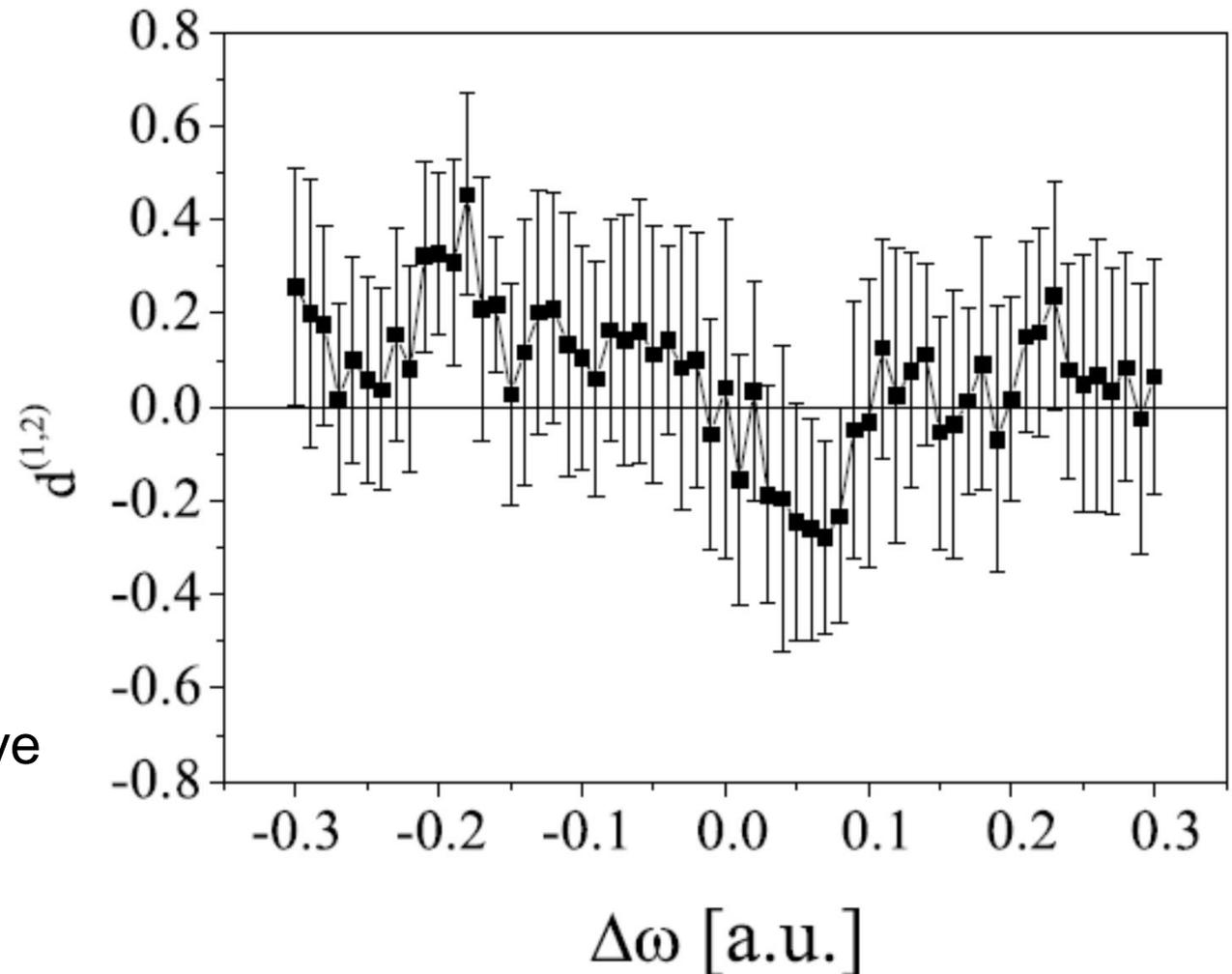
 $\omega_1 = 0.9; \omega_2 \in [0.6; 1.2]$

(20 realizations)

dependence on

frequency detuning $\Delta\omega = \omega_1 - \omega_2$ the fast system appears to drive
the other system

direction of interaction

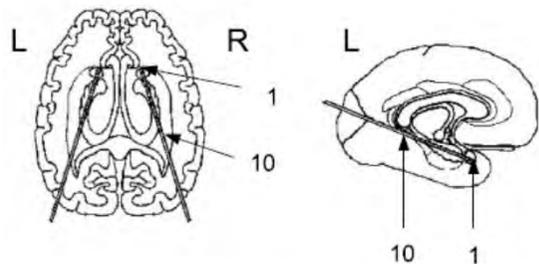
examples

measuring interactions

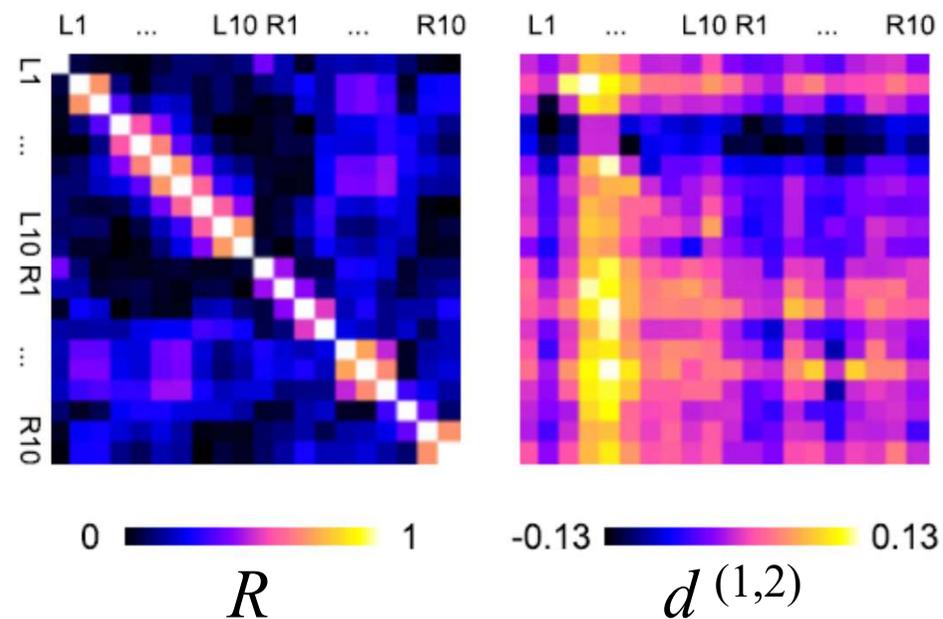
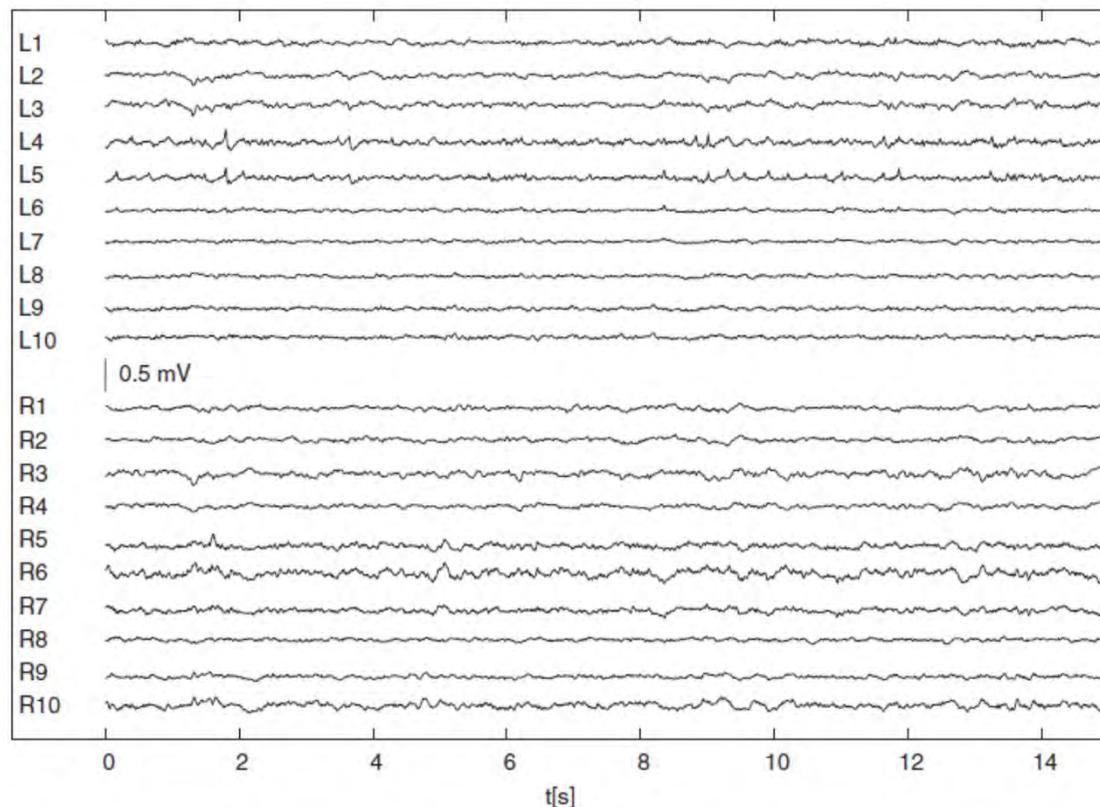
phase-synchronization

strength and direction of interaction

examples



focal driving in epilepsy



(based on ~ 150 min EEG from seizure-free interval)

measuring interactions

phase-synchronization

strength and direction of interaction

phase-based estimators

extensions

- various data-driven estimation techniques*
- estimators for transient signals**
- multivariate (partial) estimators***

*see, e.g. Porz S, Kiel M, Lehnertz K. Can spurious indications for phase synchronization due to superimposed signals be avoided?. Chaos 24, 033112, 2014.

**Wagner T, Fell J, Lehnertz K. The detection of transient directional couplings based on phase synchronization. New J. Physics 12, 053031, 2010

*** e.g. Schelter B, Winterhalder M, Dahlhaus R, Kurths J, Timmer J. Partial phase synchronization for multivariate synchronizing systems. Phys. Rev. Lett. 96, 208103, 2006;

Kralemann B, Pikovsky A, Rosenblum M. Reconstructing effective phase connectivity of oscillator networks from observations. New J Physics 16, 085013, 2014;

Rings T, Lehnertz K. Distinguishing between direct and indirect directional couplings in large oscillator networks: Partial or non-partial phase analyses?. Chaos 26, 093106, 2016

measuring interactions

phase-synchronization

strength and direction of interaction

phase-based estimators

advantages

- (relatively) easy-to-use, fast-to-calculate
- high / moderate robustness ($R / d^{(1,2)}$) against noise

disadvantages

- consider phase information only
- require appropriate choice of algorithmic parameter
- “faster” system (eigen-frequency, noise) → driver
(need reliable surrogate test for directionality)
- may be fooled by (unobserved) third system